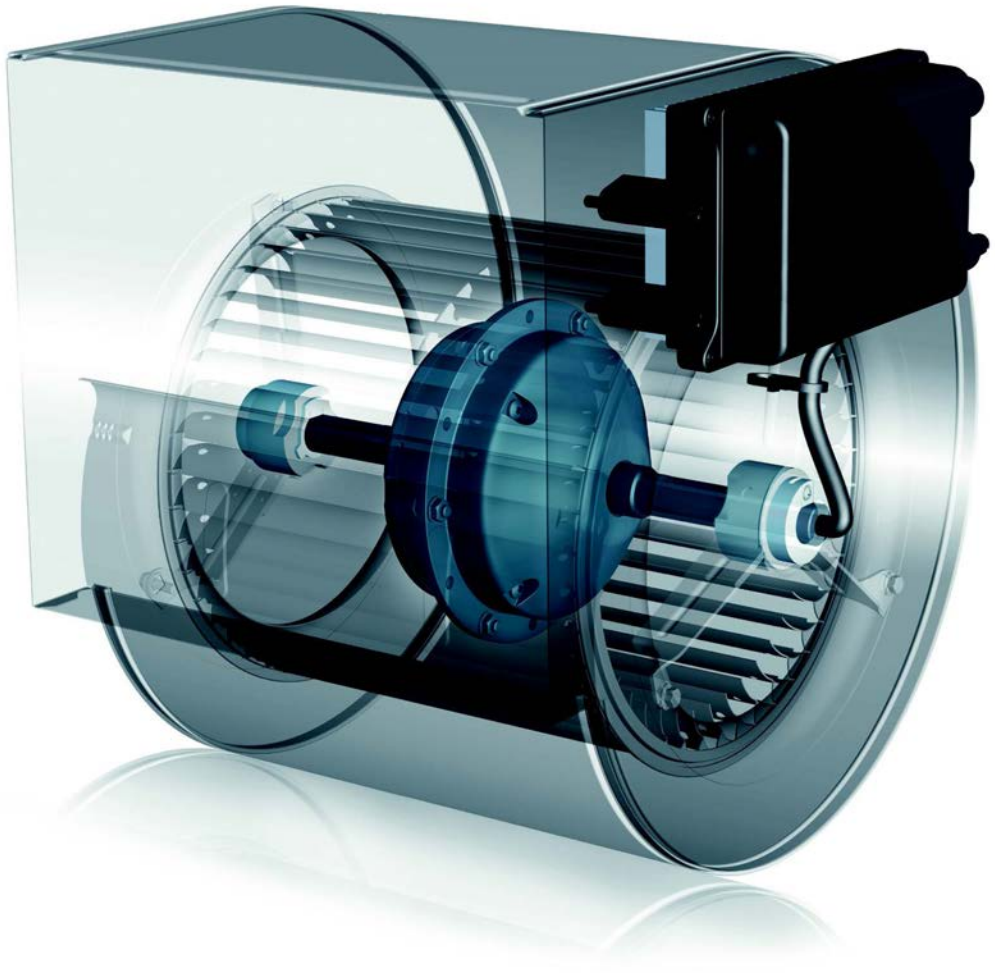
NICOTRA Gebhardt

EC FAN DDMP
OPERATING MANUAL



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1. DEFINITIONS AND WARNINGS

1.1 Object of this manual

The aim of this manual is giving instrutions concerning installation, use and maintenance of DDMP fans.

This manual refers to fans having a driver with a 5 firmware revision or higher.

1.2 Symbols used

As to the **"WARNING"** and **"CAUTION"** messages, the safety message is a symbol (a triangle containing an exclamation mark) followed by the text indicating the risk level. Its purpose is to warn the user of the potential personal damage that may result from an incorrect use of the machine or from the non-compliance with the use and maintenance instructions.
Failure to comply with these safety messages could cause damage and/or the partial or total destruction of the product or other equipment connected to it or harm people.

As to the **"NOTICE"** message, the safety message does not indicate precisely a risk, it is only for information.

Pictogram	Description
WARNING	Indicates a potential risk situation that can lead to death or serious damage, if it not prevented (ex. amputations, severe burns, loss of vision or hearing loss or visual or auditory sensorial impairment).
CAUTION	Indicates a potential risk situation that could cause less severe or minor damage, if not prevented (ex. cuts, scratches, irritation).
	NOTICE message: it is used for non-physical injuries.
	Danger to persons due to electricity.
	The operations whose execution requires qualified or specialized staff to avoid any danger are indicated with this symbol.

1.3 Qualified personnel

For this Instruction Manual and product labels, a "Qualified person" is someone who is familiar with the installation, mounting, start-up and operation of the equipment and the hazards involved. He or she must have the following qualifications:

- Trained and authorized to energize, de-energize, clear, ground and tag circuits and equipment in accordance with established safety procedures.
- Trained in the proper care and use of protective equipment in accordance with established safety procedures.
- Trained in rendering first aid.

1.4 Use for intended purpose only

The equipment may be used only for the application stated in the manual and only in conjunction with devices and components recommended and authorized by **Nicotra Gebhardt**.

1.5 Safety instructions

The following warnings, cautions and notes are provided for your safety and has a means of preventing damage to the product or components at the connected machines.
Specific warnings, cautions and notes that apply to particular activities are listed at the beginning of the relevant chapters and are repeated or supplemented at critical points throughout these sections.
Please read the information carefully, since it is provided for your personal safety and will also help prolonging the service life of your fan.

This manual is an integral part of the EC Fan DDMP and it must be carefully read before using it since it gives important indications with regards to its safe installation, use and maintenance. Keep it with care.

⚠ WARNING

Before using the EC Fan DDMP, read carefully the following general safety rules.

⚠ WARNING

The use and maintenance manual of any domestic appliance or similar device incorporating a DDMP fan shall include the following clauses.

⚠ WARNING

This appliance can be used by children aged from 8 years and above and persons with reduced physical, sensory or mental capabilities or lack of experience and knowledge on condition that they are supervised and instructed concerning use of the appliance in a safe way and understand the hazards involved.
-> Children shall not play with the appliance
-> Cleaning and user maintenance shall not be made by children without supervision

- After taking off the packaging make sure that the fan is intact. In case of doubt do not use it and contact an authorized service centre.
- Check that the fan is not damaged in any of its parts. The safety concept of the fan is valid only in perfect conditions.

RISK OF ELECTRICAL SHOCKS

- Any damaged socket, connection terminal or cable must be replaced immediately by qualified technicians or by authorized service centre.
- In case of repair or replacement of the connection cables and/or of the damaged devices or that do not work properly, please contact the authorized service centre.
- Incorrect or improper installation may cause the system to malfunction and/or result in damage to people and/or property.
- Always disconnect the power supply before opening the fan.

Any installation and/or maintenance tasks are only to be carried out by skilled, specialist personnel.
Existing electrical systems must comply with the rules in force in the country where the DDMP fan is installed.
Before doing any maintenance, make sure that the power supply and the batteries have been disconnected.
Install an all-pole disconnecting device in the power supply system (in accordance with IEC 60335-1 or IEC 60204-1, as applicable).
Conform to the wiring diagrams shown in the section “ELECTRICAL CONNECTIONS” of this manual.

1.6 Informative letter

The installer and the maintenance man must know the content of this manual. Although the main features of the equipment described in this manual are not subject to change, the manufacturer reserves the right to modify the components, details and accessories it deems necessary to improve the product or to meet manufacturing or commercial requirements at any time and without being obliged to update this manual immediately.

WARNING

The **Nicotra Gebhardt** products have not been conceived to work in areas at risk of explosions. In case of damage or malfunction, the DDMP fans must not be used until the Customer Care Technical Service has repaired it.

Customer Care Technical Service

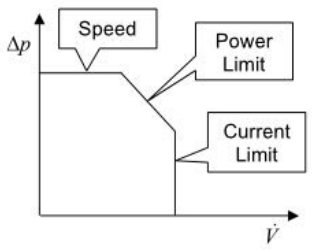
For information concerning the nearest supporting center, please get in touch with your retailer.

WARNING

The original configuration of the fan must not be changed at all, except as prescribed in this manual.
On receiving the fan, make sure the supply corresponds to what has been ordered.
In case of non-compliance immediately inform the manufacturer.
Also make sure the DDMP fan has not been damaged during transport.

1.7 Safe operating area

The drivers are protected against overload conditions and a safe operating area is defined by a limit of speed, output power and motor current.
For more details refer to the ANNEX "Analog Signal Considerations".



2. REGULATORY REFERENCES

2.1 Mechanical and electrical safety

These fans with EC drive systems are designed for incorporation in equipment, fulfilling the requirements set by the **Machinery Directive (MD - Dir. 2006/42/EU)**, and those parts of the **Low-Voltage Directive (Dir. 2014/35/EU)** which are applicable in accordance with the MD, where it concerns electrical safety.
Electrical safety is generally achieved by application of the provisions of the **EN 60204-1 standard "Electrical equipment of machines - General requirements"**.
Selected ranges may be designed to be suitable for incorporation (as components) within products which comply with the standards **EN 60335-1 "Household and similar electrical appliances - Safety - General requirements"** and **60335-2-40 "Household and similar electrical appliances - Safety - Particular requirements for electrical heat pumps, air-conditioners and dehumidifiers"**.
Such safety requirements are covered as far as necessary for a partly complete machine, sub-assembly or component, as these fans are specifically intended for incorporation within other machines.
The responsibility for the mechanical and electrical safety of the installed fan is thus of the manufacturer of the complete machine and, for this reason, it is strictly forbidden to put the fan in operation before the manufacturer of the machine has assessed and declared that the complete machine fulfils all the essential safety requirements set forth by the MD.
Please, check the Declaration of Incorporation which accompanies each product, or ask your **Nicotra Gebhardt** sales representative, for additional information.

2.2 Electro-Magnetic Compatibility [EMC]

Single-phase drive systems: DDMP 1 kW, DDMP 2 kW

The drivers of these products incorporate an Active Power Factor Control module, to provide harmonics filtering and compliance with the EMC requirements applicable to domestic and equivalent environments ("first environment"), or with the advanced requirements for harmonic distortion which often apply to data centers.
More specifically: they comply with the requirements set in

EN 61000-6-3 – Electromagnetic compatibility (EMC). Part 6-3: Generic standards. Emission standard for residential, commercial and light-industrial environments.

Three-phase drive systems: DDMP 2.6 kW, DDMP 4kW
The drivers of these products are provided with basic EMI filters only.
They are suitable for use in the "first environment", under condition that they are incorporated into an apparatus, system or installation, which is neither a plug-in device nor a movable device.
Such devices shall have to be installed and commissioned only by a professional.
More specifically: they comply with the requirements set in

EN 61000-6-4 – Electromagnetic compatibility (EMC). Part 6-4: Generic standards - Emission standard for industrial environments which this product is incorporated must comply with the EMC Directive 2004/108/EC.

Specific electrical safety and EMC standards are applied according to the available models of conformity declaration (identified as 985732, 985740 and 985748):

		EMC standards	
		61000-6-3 (household)	61000-6-4 (industrial)
Electrical safety standards	60204 (machines)	985732	985748
	60335 (domestic appliances)	985740	n/a

To improve the Electromagnetic compatibility a ferrite should be put on the power supply cable (close to the driver). The compliancy to the standards is intended for a single fan. No tests have been made on multiple installations.

The compliancy to the standards are intended for a single fan.
No tests have been made on multiple installations.

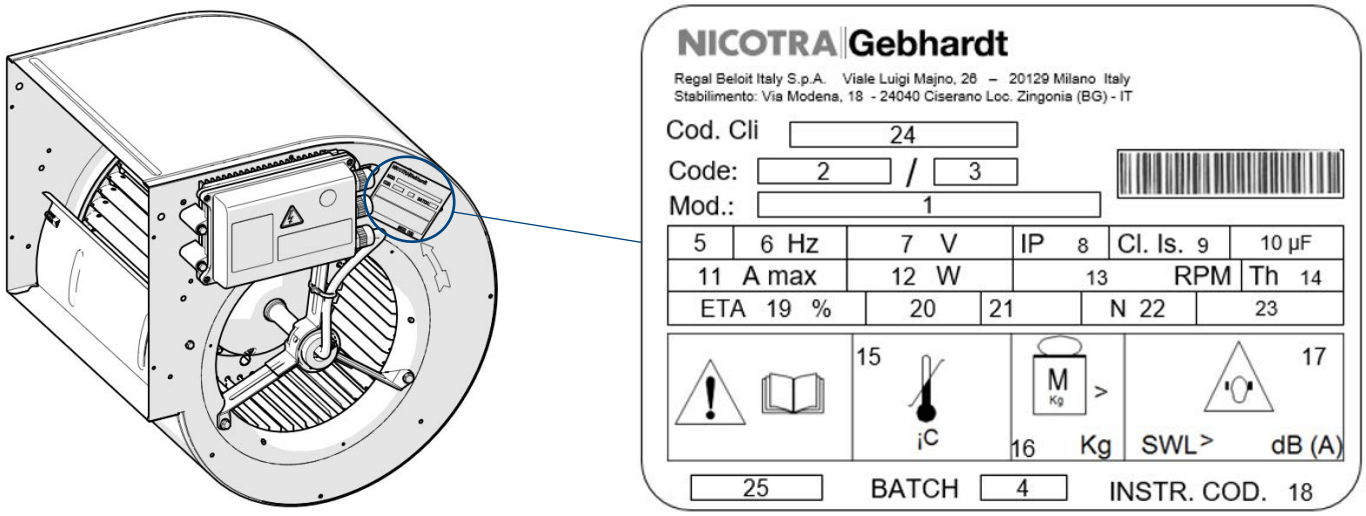
⚠ WARNING

The EMC tests are conducted without 485 communication wire, analog signals or Bluetooth devices.

3. DATA PLATE

The manufacturer's identification plate is located on the fan.
Several safety warnings are applied to the fan; such warnings must be strictly followed by everyone dealing with this product.
The company is not to be held responsible for damage to property or accidents to people which might occur if the above-mentioned warnings are not observed. In such a case, the operator is the only person responsible.

The identification plate is located on the fan scroll case.



REF.	DESCRIPTION
1	MODEL DESIGNATION
2	REGAL BELOIT ITALY CODE
3	MODIFICATION LEVEL
4	PRODUCTION LOT NO.
5	NO. PHASES & CURRENT TYPE
6	ELECTRICAL FREQUENCY
7	VOLTAGE
8	IP PROTECTION GRADE
9	MOTOR INSULATION CLASS
10	CAPACITOR VALUE (WHEN PRESENT)
11	MAXIMUM CURRENT INPUT
12	MOTOR RATED POWER
13	RATED RPM

REF.	DESCRIPTION
14	THERMAL PROTECTOR (Y/N)
15	OPERATING TEMPERATURE RANGE
16	UNIT EXCEEDS 30KG (Y/N)
17	UNIT EXCEEDS 85 dB (A) SOUND POWER (Y/N)
18	OPERATING MANUAL
19	OVERALL EFFICIENCY (η)
20	EFFICIENCY CATEGORY (STATIC OR TOTAL)
21	MEASUREMENT CATEGORY USED TO DETERMINE THE ENERGY EFFICIENCY (A-D)
22	EFFICIENCY GRADE AT OPTIMUM ENERGY EFFICIENCY POINT
23	ErP COMPLIANCE
24	CUSTOMER CODE (WHEN APPLICABLE)
25	PRODUCTION DATE

4. TRANSPORT & STORAGE

⚠ WARNING

Correct transport, storage, erection and mounting, as well as careful operation and maintenance are essential for proper and safe operation of the equipment.
Protect the fan against physical shocks and vibration during transport and storage. Also, be sure to protect it against water (rainfall) and excessive temperatures.

⚠ CAUTION

If the fan must be subject to long-term storage, the storage time without application of any power supply shall not exceed two years since fan production or since operating the fan for at least half-an-hour continuously.
The storage site shall have a temperature between -20°C and +70 °C, a Relative Humidity lower than 75%, and not be subject to condensation or exposed to dust.

5. PACKING CONTENTS

The fan is delivered in a cardboard box inside which there are the installation instructions and the options required by the Customer at time of order. All these options will be mounted directly by the Manufacturer.

Apart from the "options", the Customer can order "accessories" afterwards. In this case, the Customer will have to install them by him/herself.

The following data are printed on the packing itself:

REF.	DESCRIPTION
1	ART. CODE
2	MODEL DESCRIPTION
3	BATCH CODE

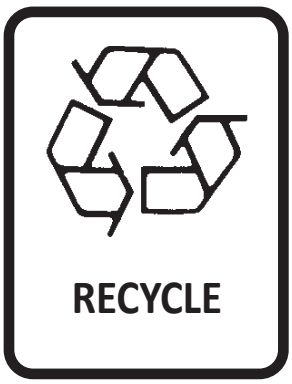
6. UNPACKING

1. Remove the fan from the box.
2. Remove all the components from the packaging.

WARNING

Check the fan. Before installing the DDMP fan, check to ensure that all of the items listed are present and that there are no visible signs of damage.

Dispose of all packing components in compliance with the laws in force in the country of use.



7. PRODUCT DESCRIPTION

The Fans of series DDMP combine high energy efficiency and low noise level. Thanks to the “EC” (electronic commutation) motors, their electronics integrate speed control and protecting system. This reduces the number of different components required to provide these functions, compared to fans with traditional motors.

The main feature of EC-motor is operating without slip losses, which allow consuming significantly less power than conventional AC motors.

This occurs at all speed levels, especially with partial load operation. The EC complete drive system (i.e. the combination of the permanent-magnet motor with its electronic driver) has a much higher energy efficiency, in comparison with a drive system based on a conventional AC motor.

Energy saving system

- High efficiency EC-motor
- Compact and streamlined motor design
- High intensity neodymium magnets
- No obstruction of intake due to build-on control unit - less aerodynamic losses

General Features

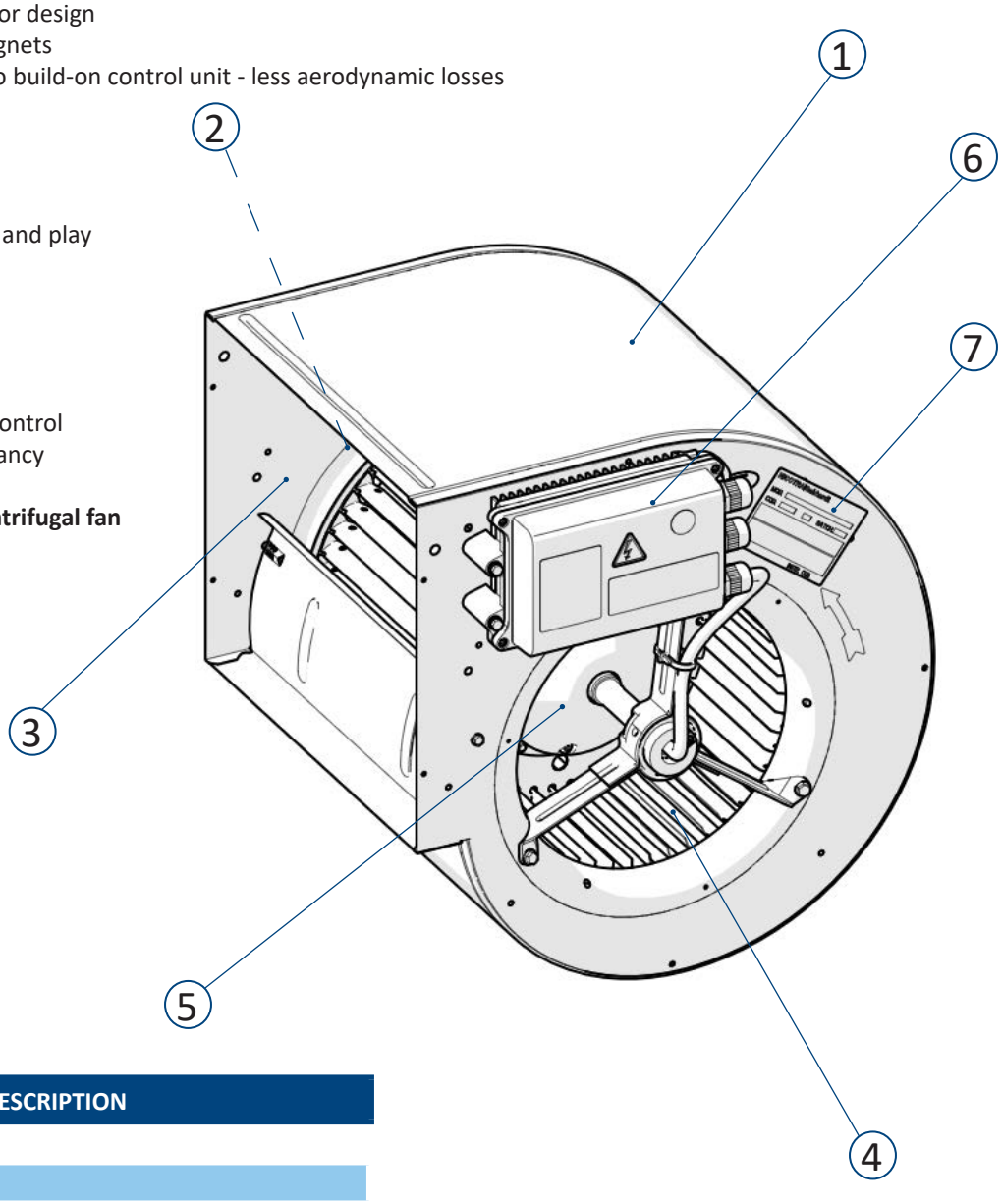
- Sensorless control
- Simple installation due to plug and play
- IP 54 for complete drive
- Designed for double inlet fans

Interface

- Analogue interface for speed control
- Full MODBUS interface compliancy

High efficiency of direct driven centrifugal fan

- Integrated solution
- Top rating efficiency
- Plug and play operation
- No need to configure long lists of inverter parameters
- Low sound level
- High reliability



REF.	DESCRIPTION
1	Scroll
2	Inlet port
3	Outlet port
4	Rotor (forward-curved blades)
5	EC motor
6	Driver
7	ID plate

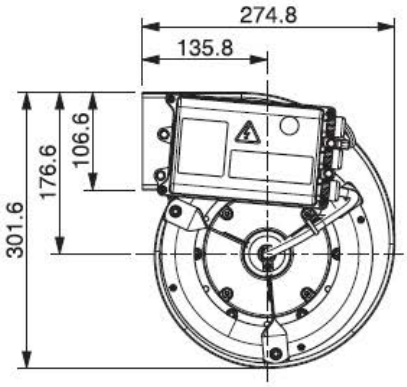
8. TECHNICAL FEATURES

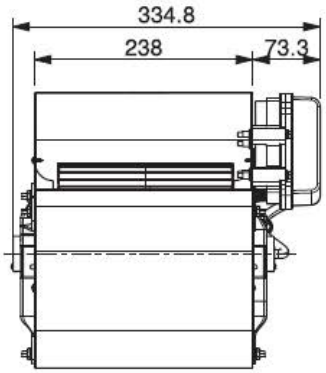
	Motor code	Driver code	Driver phases	Abs. curr. (A)	Abs. pow. (W)	Min. temp. (°C)	Max. temp. (°C)	IP class protection
7/7T	1416A3	1431A5	1 Ph	4.59	1065	-20°C	+40°C	IP 55
7/7	1416A0	1431A5	1 Ph	4.62	1074	-20°C	+40°C	IP 55
7/9	1416A1	1431A5	1 Ph	4.5	1048	-20°C	+40°C	IP 55
8/7T	1416A0	1431A5	1 Ph	4.5	1052	-20°C	+40°C	IP 55
8/9T	1416A1	1431A5	1 Ph	4.5	1049	-20°C	+40°C	IP 55
9/7	1416A0	1431A5	1 Ph	4.51	1035	-20°C	+40°C	IP 55
9/9	1416A1	1431A5	1 Ph	4.5	1040	-20°C	+40°C	IP 55
9/9	1416A4	1431A8	1 Ph	9.42	2213	-20°C	+40°C	IP 55
9/9	1416A4	1431G0	3 Ph	3.43	2140	-20°C	+40°C	IP54
225/240	1416A1	1431A5	1 Ph	4.48	1044	-20°C	+40°C	IP 55
10/8	1416A2	1431A5	1 Ph	4.51	1036	-20°C	+40°C	IP 55
10/8	1416A4	1431A8	1 Ph	9.42	2208	-20°C	+40°C	IP 55
10/8	1416A4	1431G0	3 Ph	3.43	2210	-20°C	+40°C	IP54
10/10	1416A2	1431A5	1 Ph	4.38	1029	-20°C	+40°C	IP 55
10/10	1416A4	1431A8	1 Ph	9.53	2202	-20°C	+40°C	IP 55
10/10	1416A4	1431G0	3 Ph	3.34	2150	-20°C	+40°C	IP54
12/9	1416A4	1431A8	1 Ph	7.66	1764	-20°C	+40°C	IP 55
12/9	1416A4	1431G0	3 Ph	2.88	1850	-20°C	+40°C	IP54
12/12	1416A4	1431A8	1 Ph	7.49	1789	-20°C	+40°C	IP 55
12/12	1416A4	1431G0	3 Ph	2.81	1810	-20°C	+40°C	IP54

Other data related to the technical features are reported on the ID plate shown in chapter 3.

8.1 Dimensional drawings

6M04A8 - DDMP 7/7 TIG 1416A3 + DRIVER





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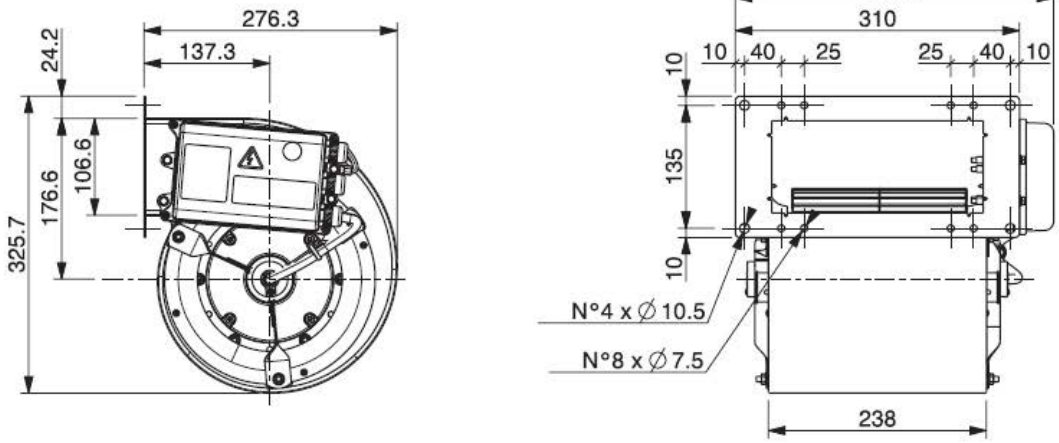

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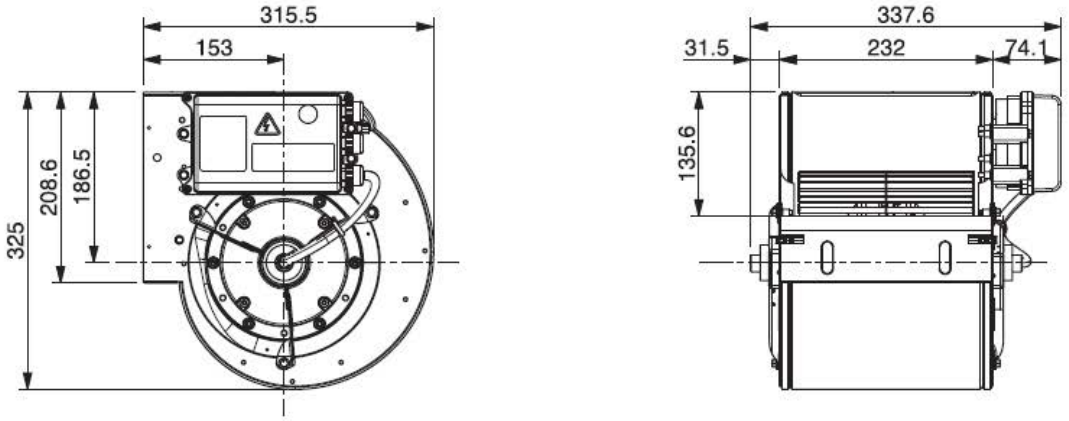

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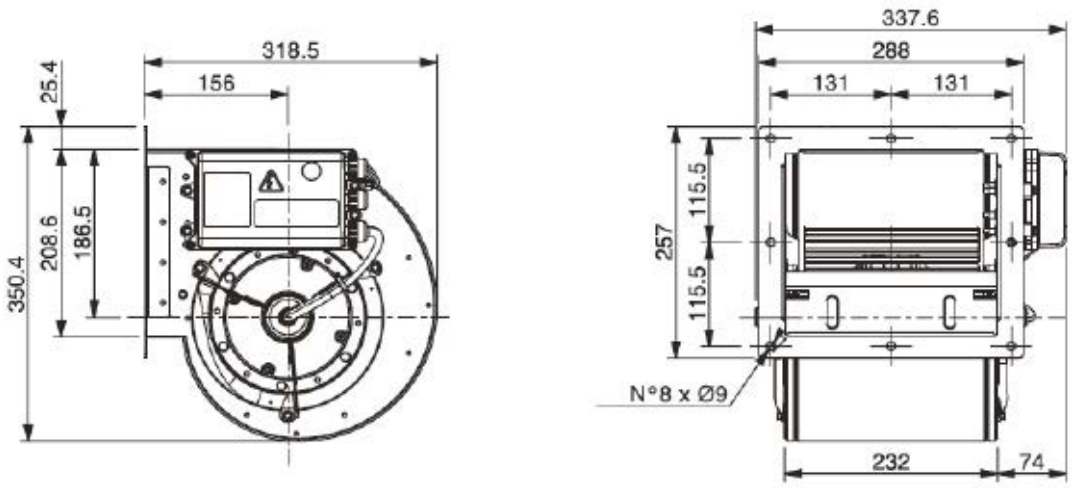

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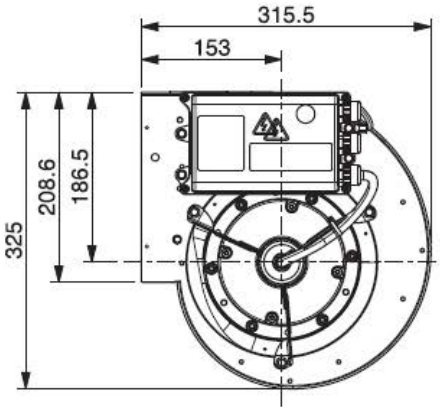

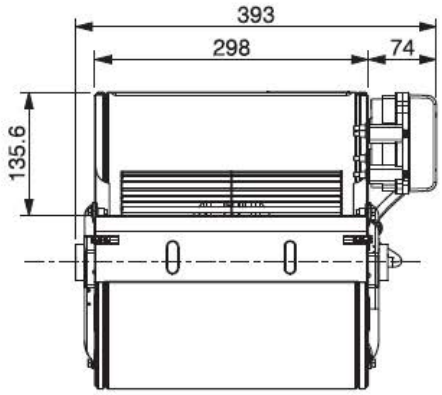

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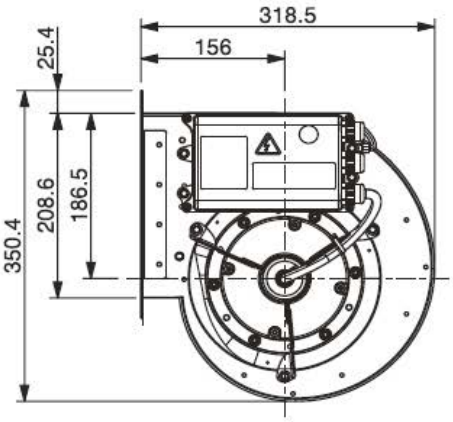

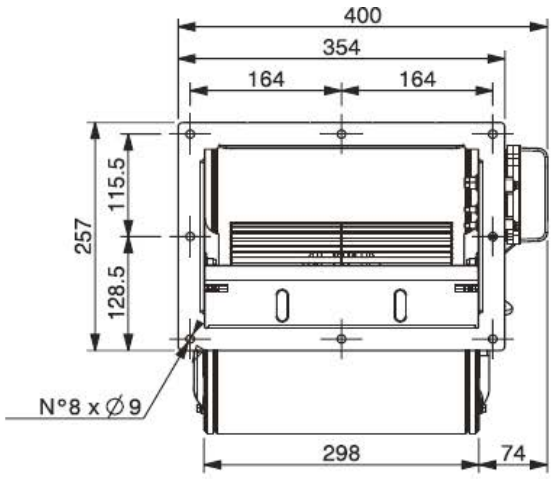

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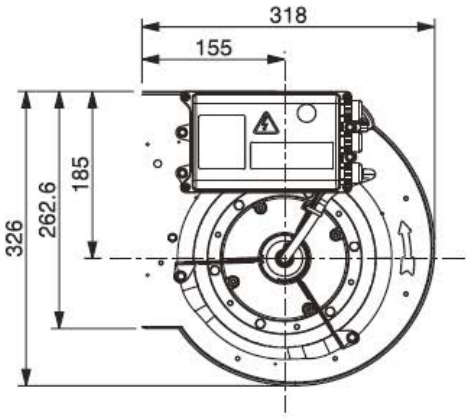

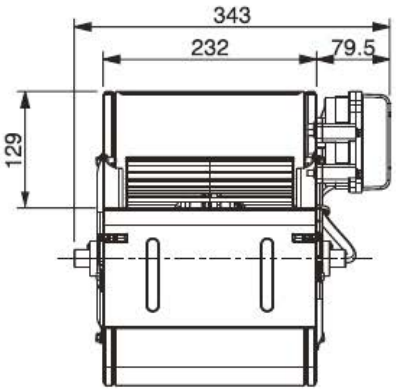

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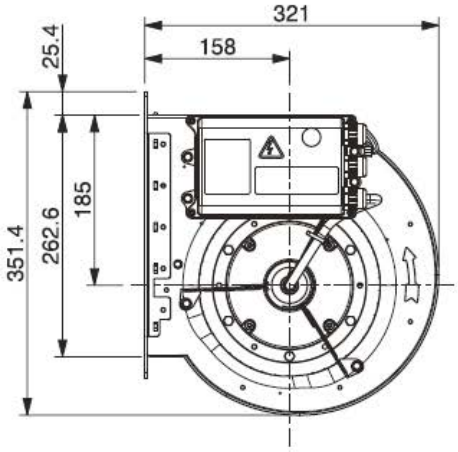

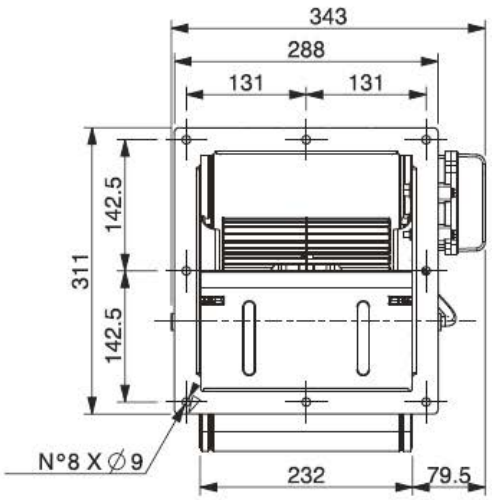

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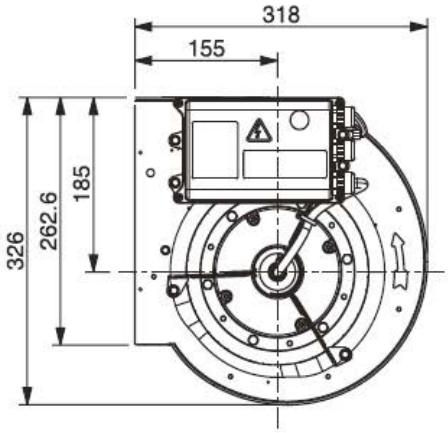

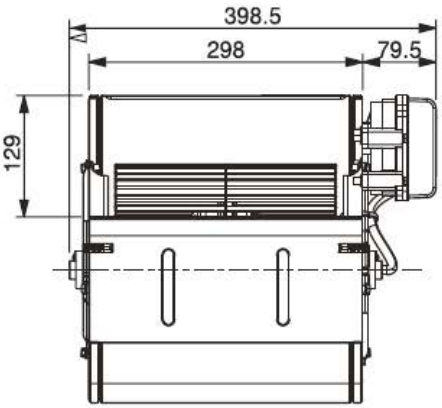

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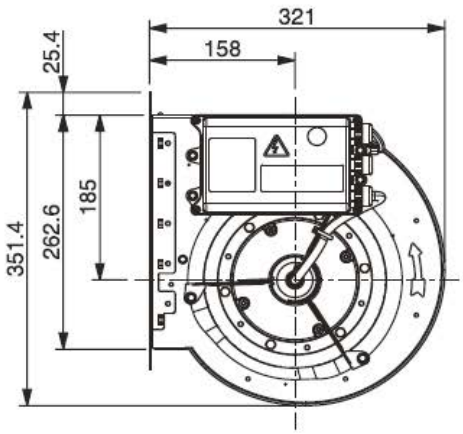

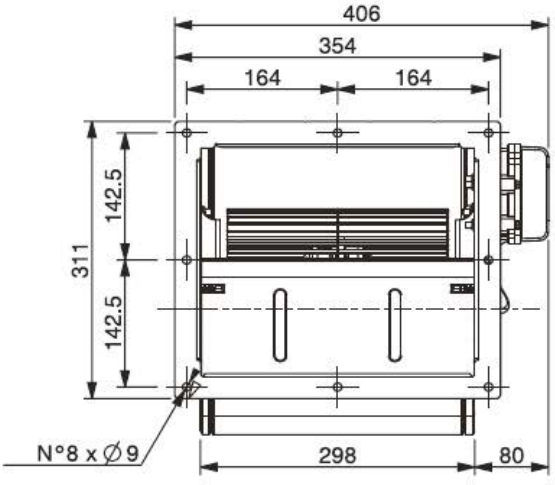

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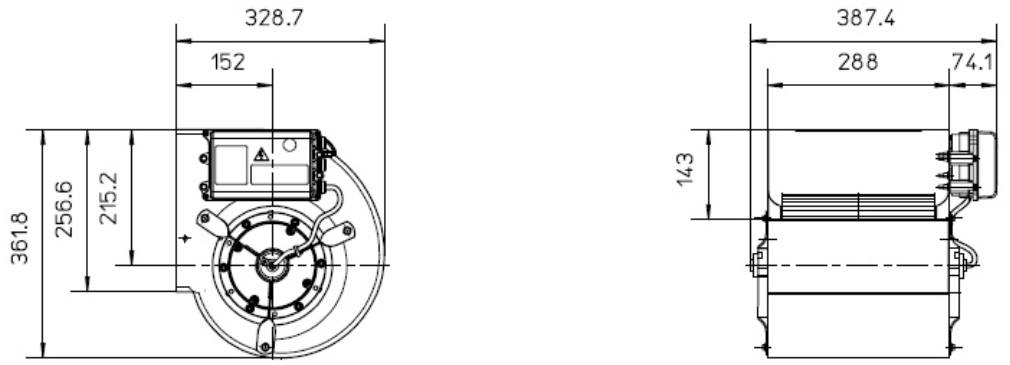

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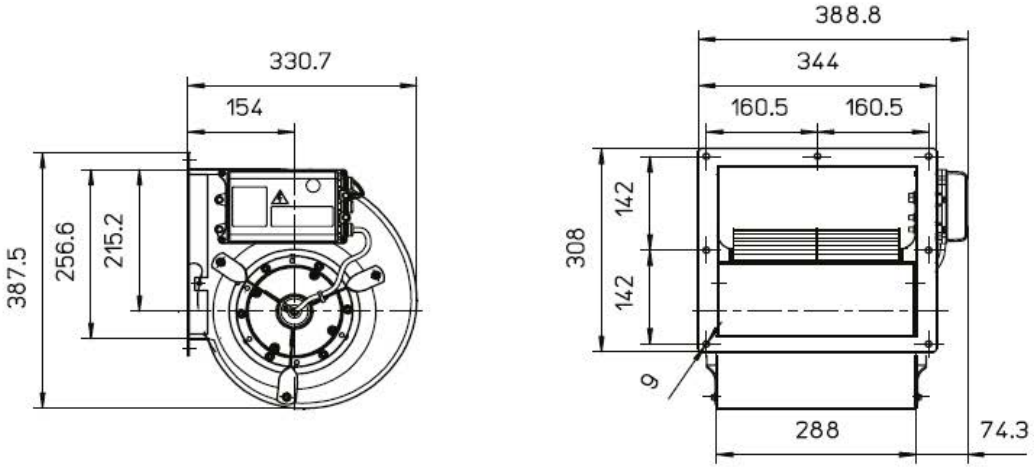

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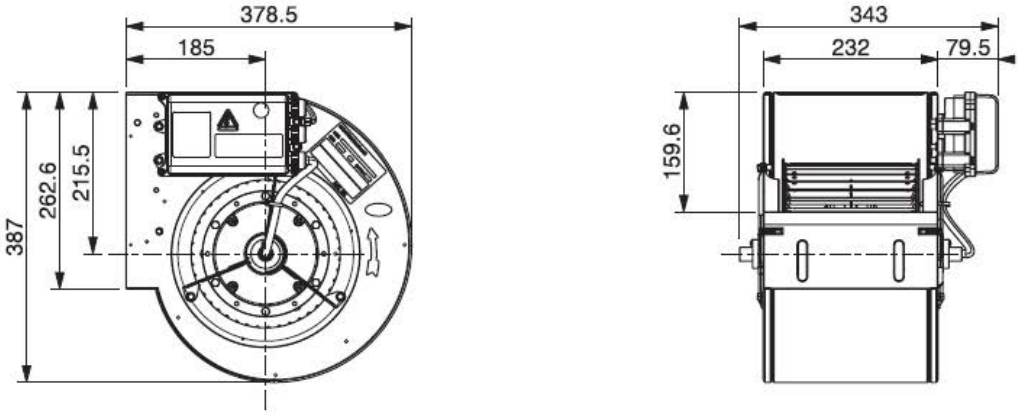

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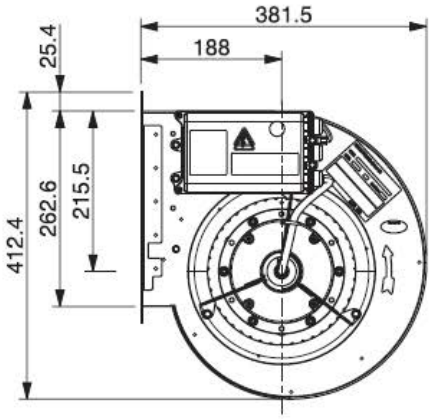
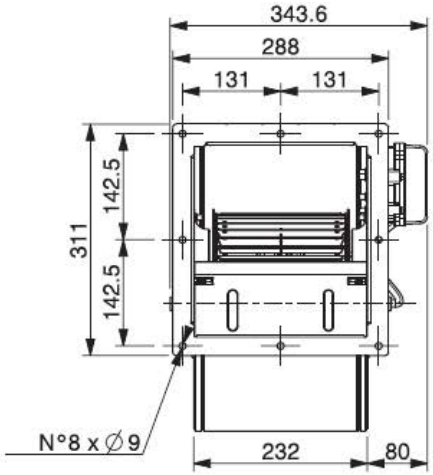
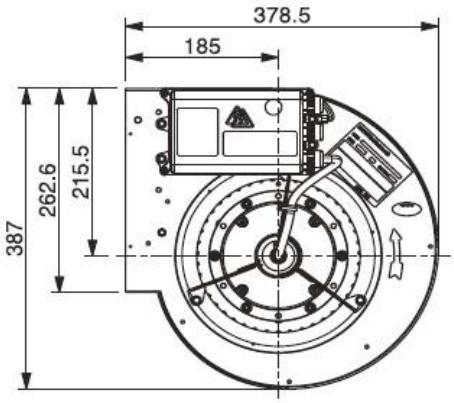
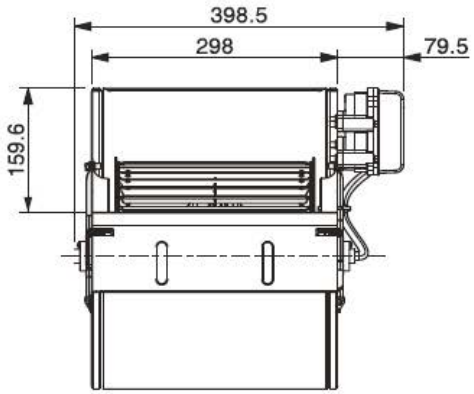


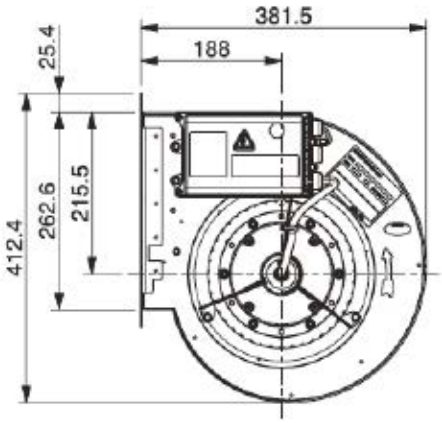


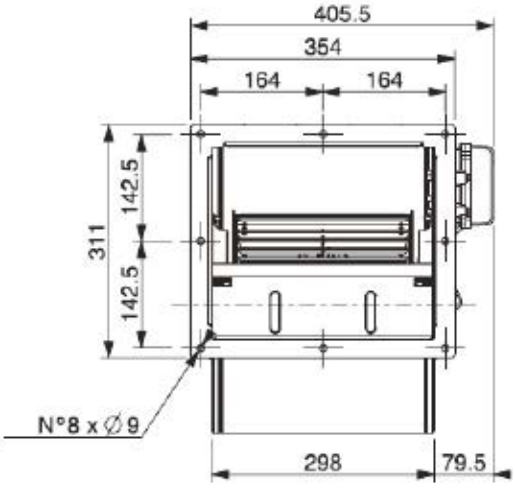
6M04A2 - DDMP 9/9 1416A1 + DRIVER



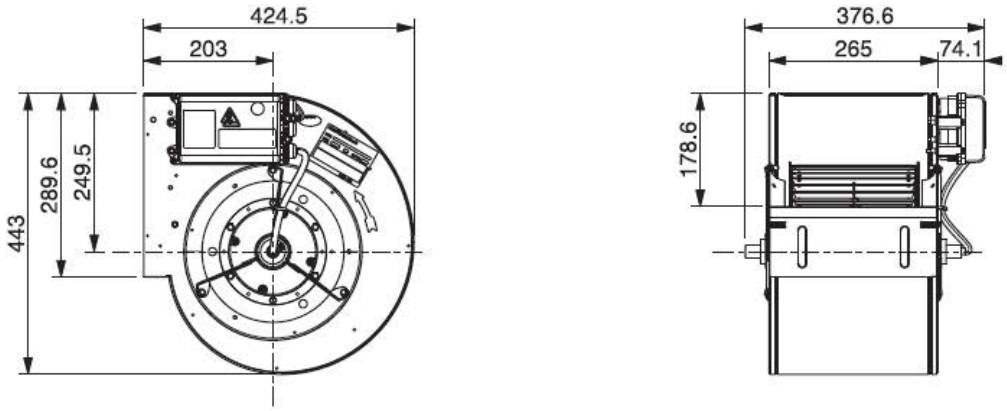


6M04E2 - DDMP 10/8 1416A1 + DRIVER + FL

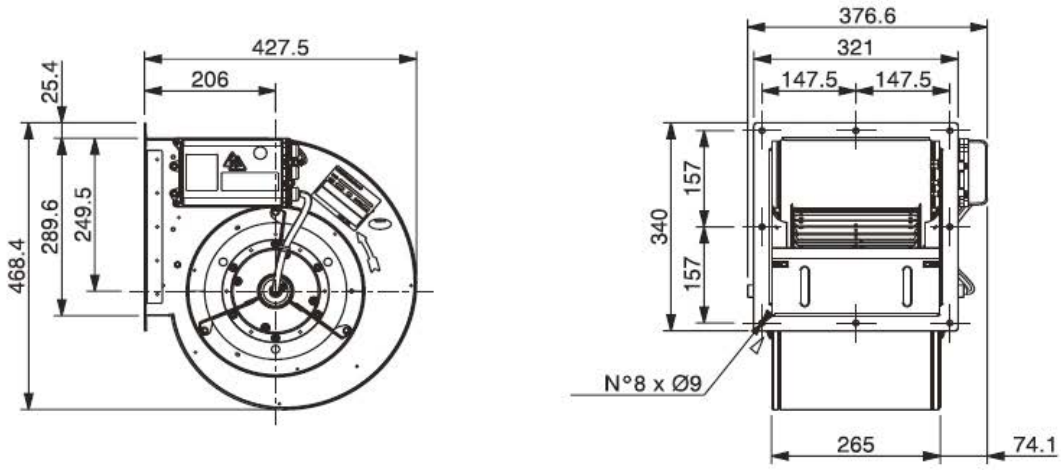




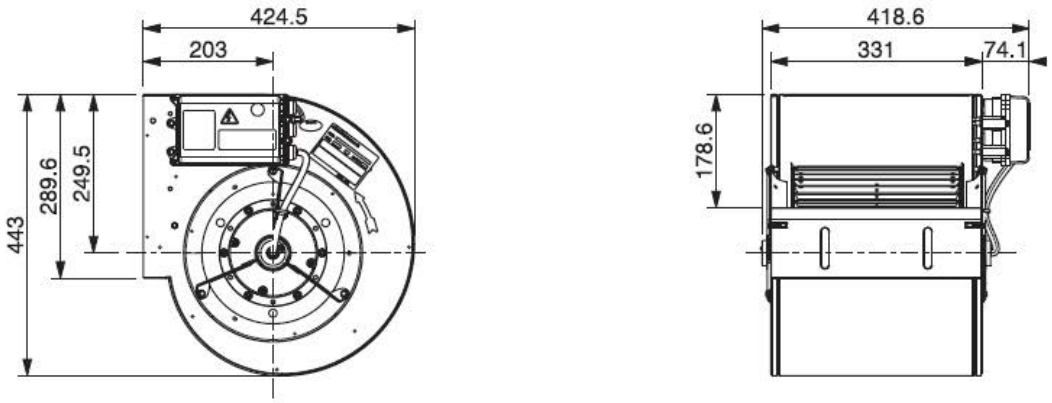
6M04A3 - DDMP 10/8 1416A2 + DRIVER



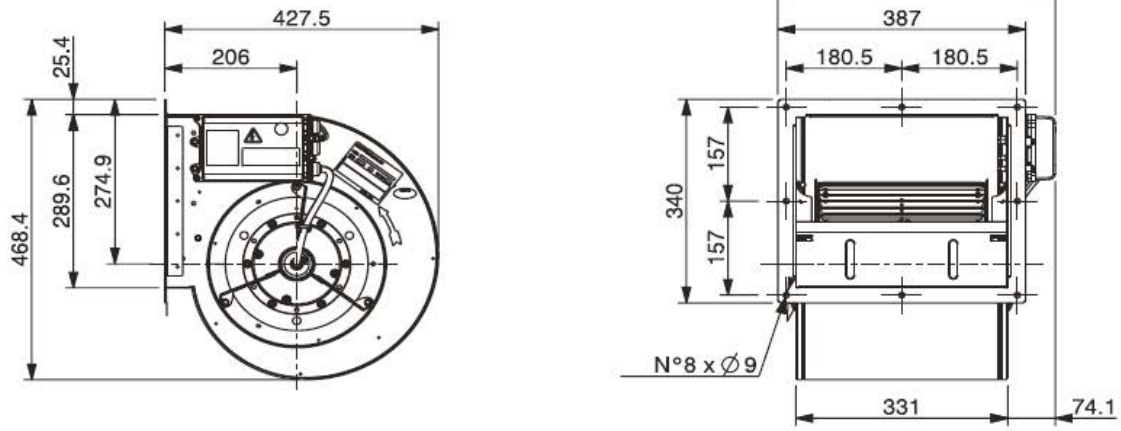
6M04E3 - DDMP 10/8 1416A2 + DRIVER + FL



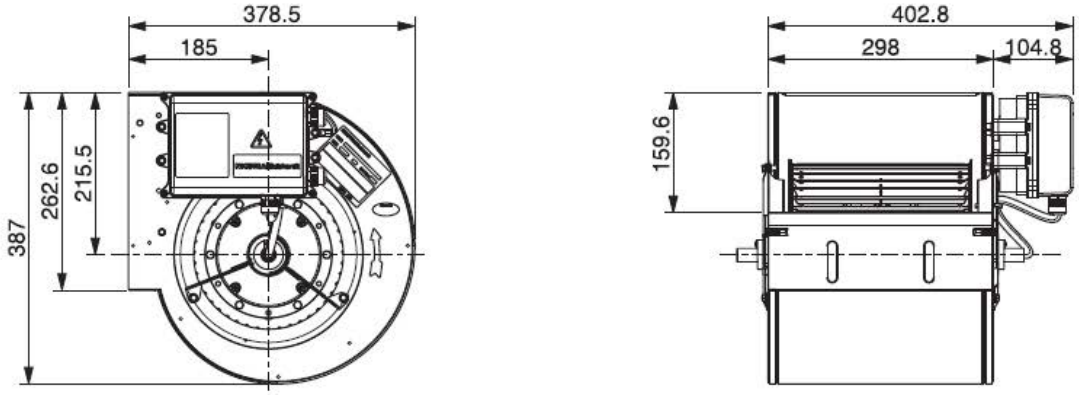
6M04A4 - DDMP 10/10 1416A2 + DRIVER



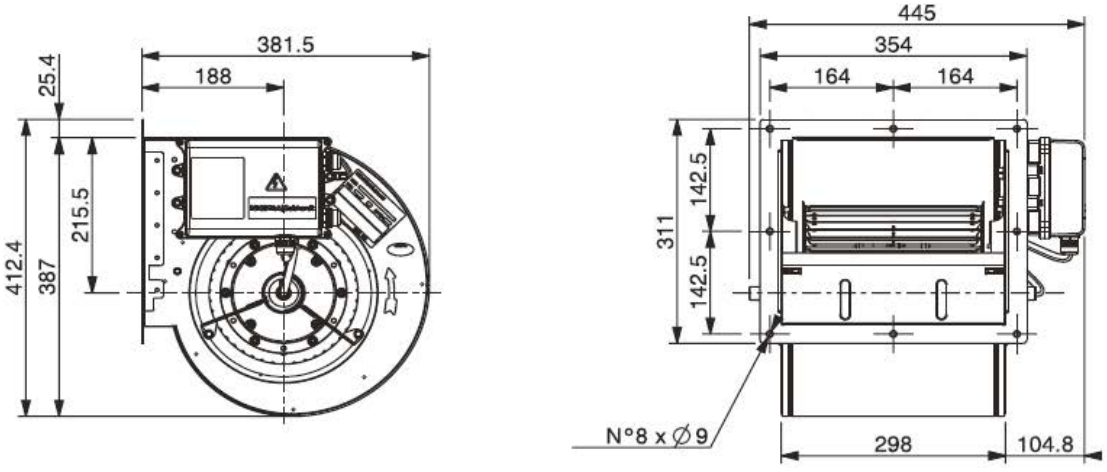
6M04E4 - DDMP 10/10 1416A2 + DRIVER + FL



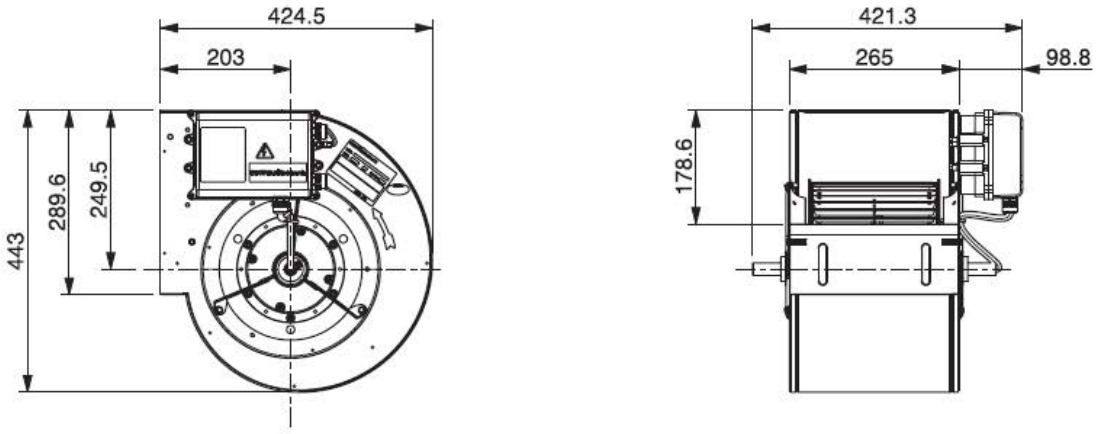
6M04H0 - DDMP 9/9 1416A4 + DRIVER



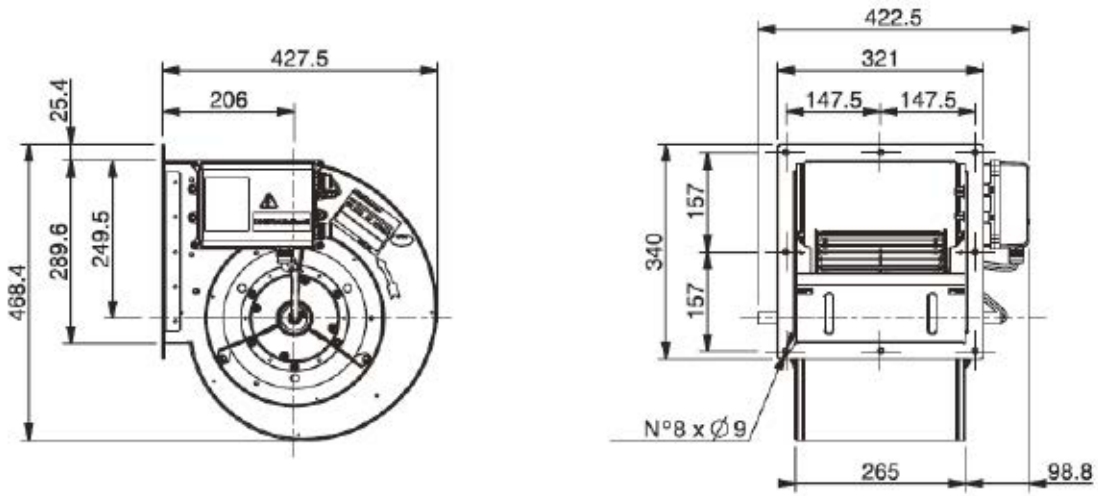
6M04K0 - DDMP 9/9 1416A4 + DRIVER + FL



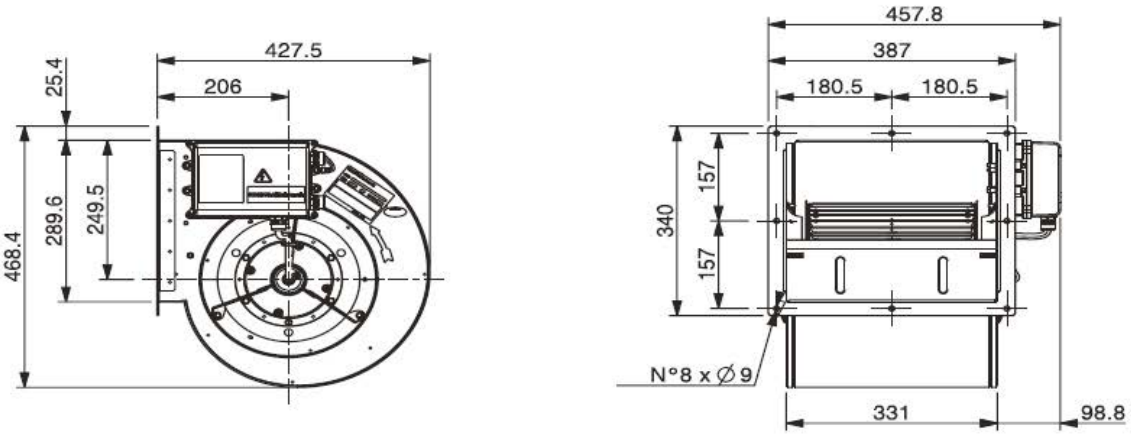
6M04H1 - DDMP 10/8 1416A4 + DRIVER



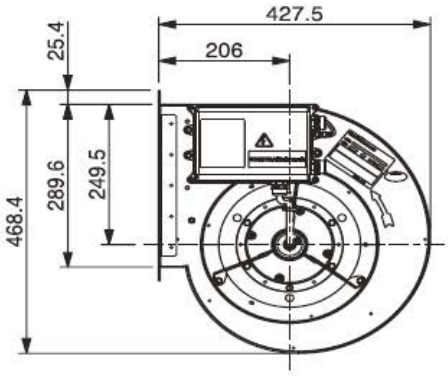
6M04K1 - DDMP 10/8 1416A4 + DRIVER + FL

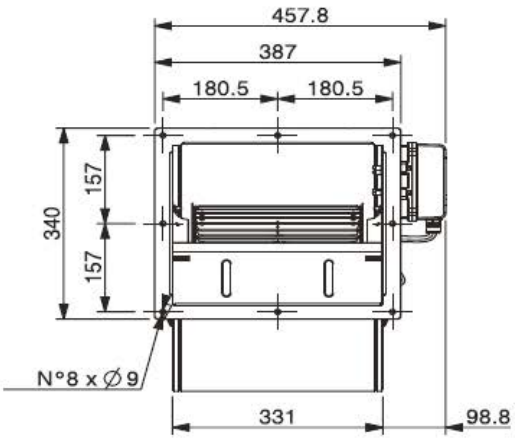


6M04H2 - DDMP 10/10 1416A4 + DRIVER

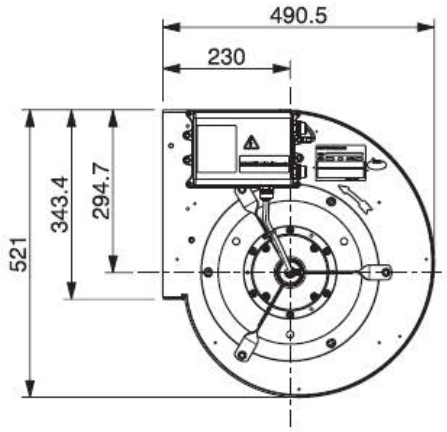


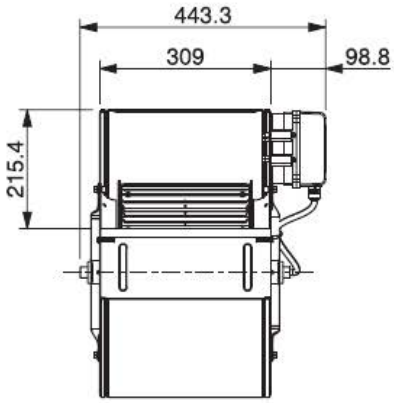
6M04K2 - DDMP 10/10 1416A4 + DRIVER + FL



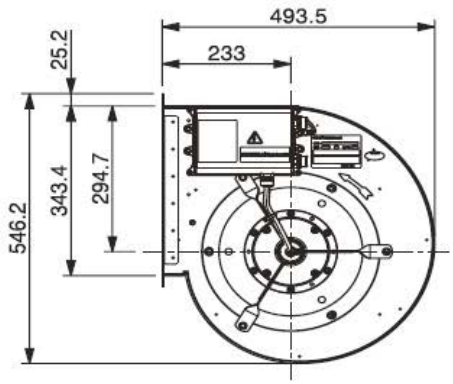


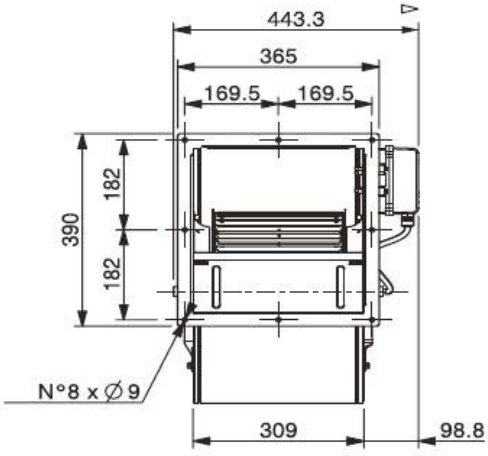
6M04H3 - DDMP 12/9 1416A4 + DRIVER



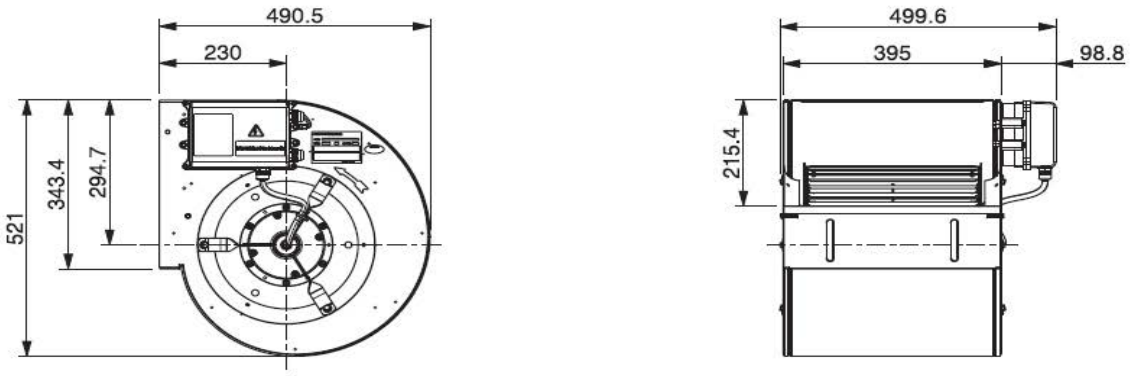


6M04K3 - DDMP 12/9 1416A4 + DRIVER + FL

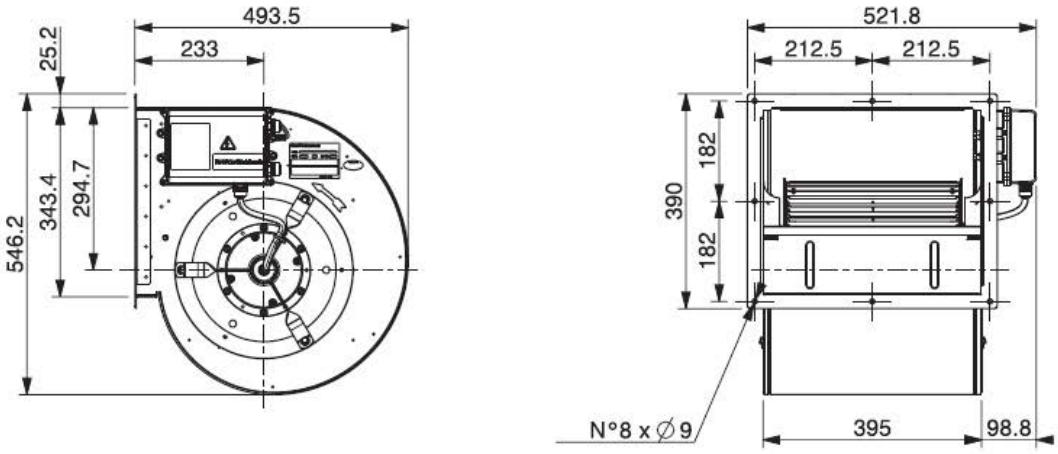




6M04H4 - DDMP 12/12 1416A4 + DRIVER



6M04K4 - DDMP 12/12 1416A4 + DRIVER + FL

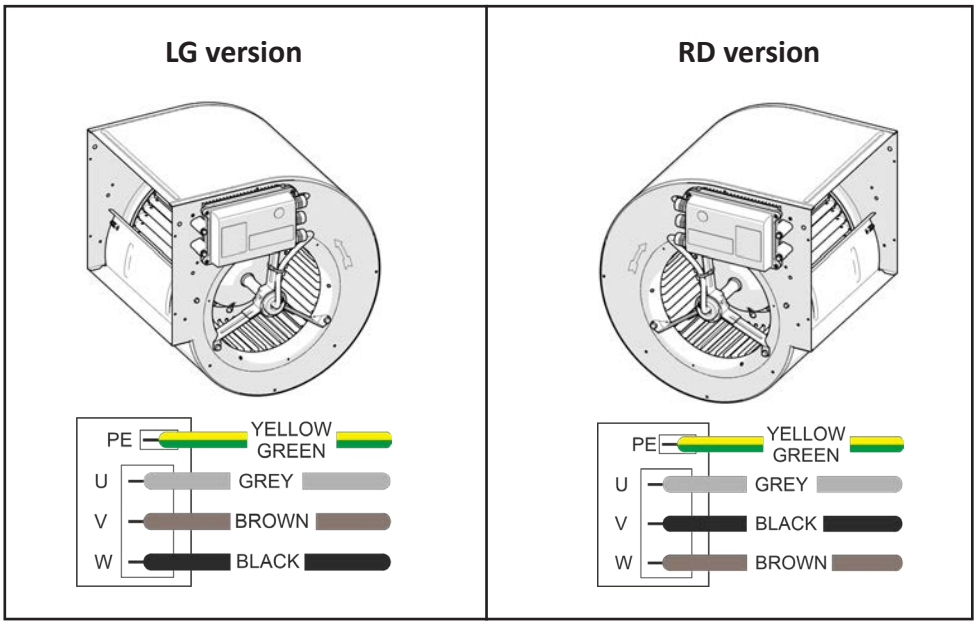


8.2 LG and RD versions

In its standard configuration, the fan is delivered in LG version (counter-clockwise rotation).
For accessibility needs, the fan can be required in RD version (clockwise rotation).
Each version is supplied with different motor connections with the printed circuit board of the drivers.

⚠ WARNING

These connections are carried out by Nicotra Gebhardt and cannot be modified by the end user.



9. INSTALLATION

The fan installation must be carried out only by competent and qualified staff.

WARNING

In the final installation, the device shall be directly connected to the supply terminals and shall have a contact separation in all poles, providing full disconnection under overvoltage category III conditions.

9.1 Commisioning

WARNING

Work on the device/system by unqualified personnel or failure to comply with warnings can result in severe personal injury or serious damage to material.
Only suitably qualified personnel trained in the setup, installation, commissioning and operation of the product should carry out work on the device/system.
The DDMP fan must be grounded through the PE connector on the driver.
The following terminals can carry dangerous voltages even if the driver is inoperative:

- **the power supply terminals L, N or R, S, T**
- **the motor terminals U, V, W**

9.2 Operation

WARNING

The driver must NOT be removed from the related DDMP fan type and size.
The driver cannot be used separate from the related fan.

WARNING

Ensure correct grounding connections. The ground cable must be enough to carry the maximum supply fault current which normally will be limited by the fuses or MCB. Suitably rated fuses or MCB should be fitted in the main supply to the driver, according to any local legislation or codes.

CAUTION

The driver operates at high voltages.
Certain parameter settings may cause the driver to restart automatically after an input power failure.

9.3 Ambient operating conditions

CAUTION

The installation place must be in accordance with the IP protection degree of the fan. In this respect, refer to the ID plate described in chapter 3.

Humidity Range: 90% non-condensing
Altitude: if the fan is to be installed at an altitude > 1000m, derating is required.
Shocks: do not drop the fan or expose it to sudden shock.
Vibration: do not install the fan in an area where it is likely to be exposed to constant vibrations.

9.4 Fan installation

Place the fan according to your needs, after having checked its dimensions and the position of the fixing holes.

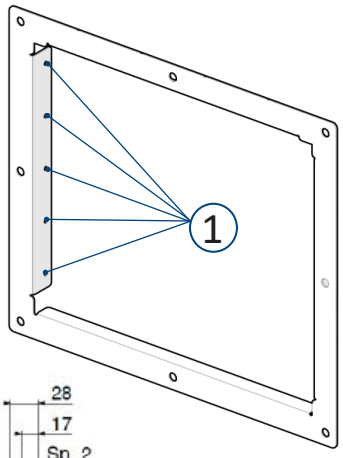
9.5 Accessory installation

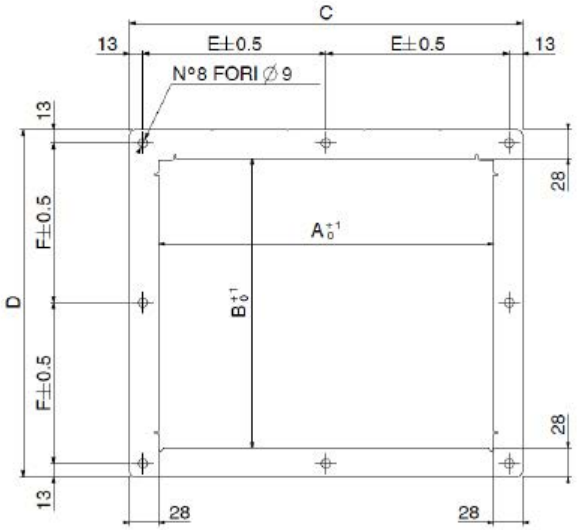
As previously mentioned, all the required options are generally installed by the Manufacturer before delivery.
The following describes the composition, the main features and the mounting procedure of each accessory that is ordered separately.

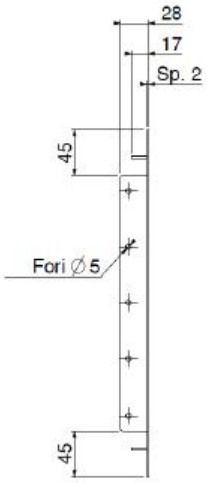
9.5.1 Outlet flanges

Materials
Galvanized steel accordirng to EN 10346 standard.

Assembly
The outlet flanges are fitted with Ø5 holes **"1"** on three sides which must be coupled on the scroll.
The flange must be assembled with the two edges external to the side plate, whereas the edge which is in contact with the back plate must be within the scroll.
The flanges can be fixed to the scroll using bolts M5 or Ø4,8 SS rivets.





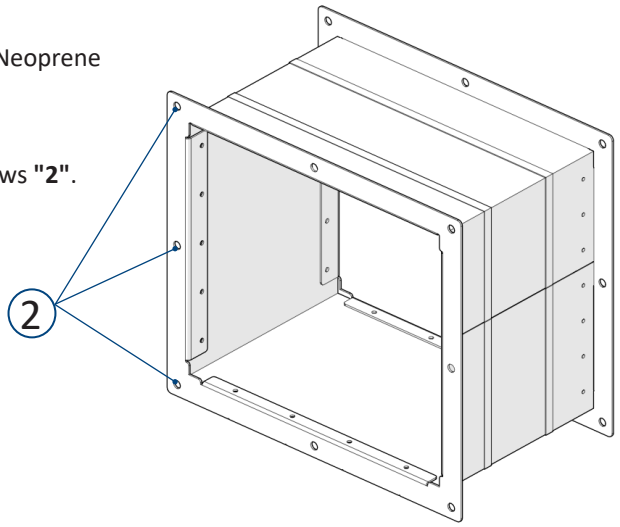


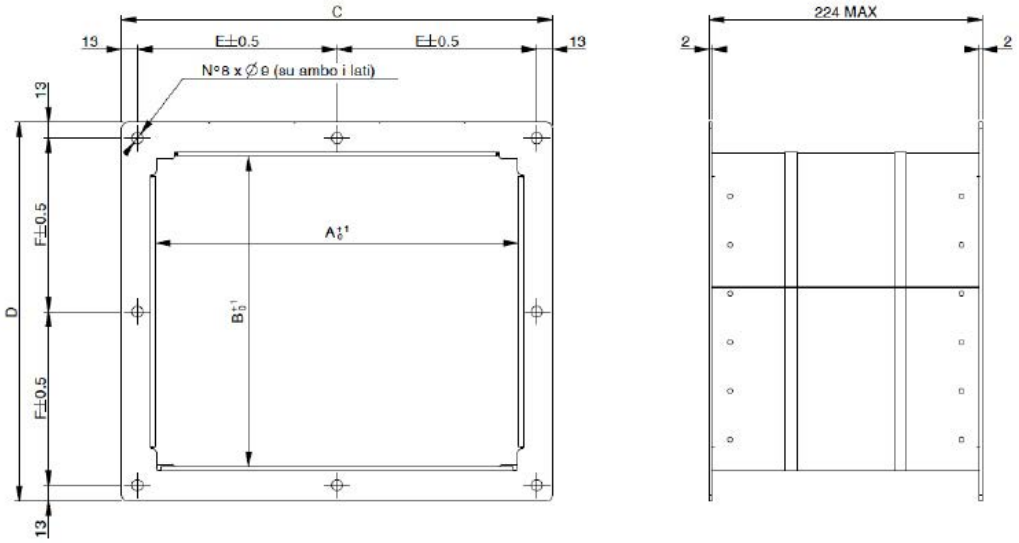
Size	Code	A	B	C	D	E	F
7/7	RA60033ZZ0000000	232	201	288	257	131	115,5
7/9	RA60053ZZ0000000	298	201	354	257	164	257
9/7-8/7 Tig *	RA60035ZZ0000000	232	255	288	311	131	142,5
9/9-8/9 Tig **	RA60055ZZ0000000	298	255	354	311	164	142,5
10/8	RA60046ZZ0000000	265	284	321	340	147,5	157
10/10	RA60066ZZ0000000	331	284	387	340	180,5	157
12/9	RA60058ZZ0000000	309	334	365	390	169,5	182
12/12	RA60088ZZ0000000	395	334	451	390	212,5	182
15/11	RA6007BZZ0000000	373	397	429	453	201,5	213,5
15/15	RA600BBZZ0000000	471	397	527	453	250,5	213,5
18/13	RA6009CZZ0000000	430	471	486	527	230	250,5
18/18	RA600CCZZ0000000	557	471	613	527	293,5	250,5
* USABLE ALSO WITH OLD SCROLLS 9/7 TIGHT							
** USABLE ALSO WITH OLD SCROLLS 9/9 TIGHT							

9.5.2 Outlet flexible connection

Materials
Flange in galvanized steel according to EN 10346 standard. Polyester / Neoprene fabric with galvanized metal strips 5/10.

Assembly
Couple and bolt the flexible connection to the fan flange using M8 screws **"2"**.



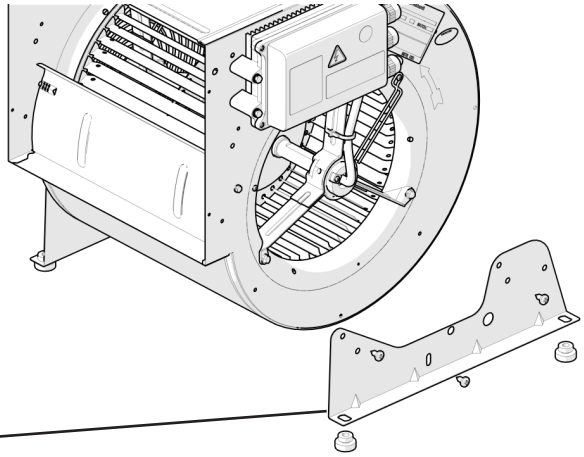


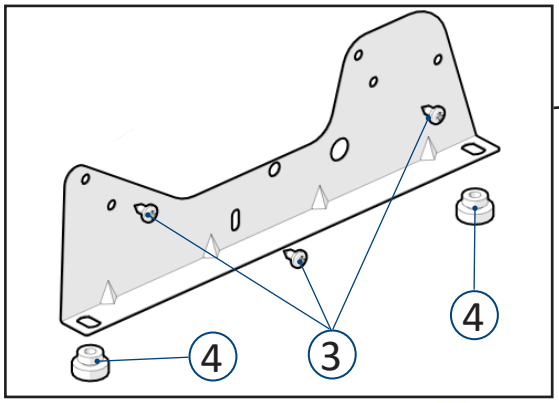
Size	Code	A	B	C	D	E	F
7/7	R609A0	232	201	288	257	131	115,5
7/9	upon request	298	201	354	257	164	257
9/7-8/7 Tig *	R609A1	232	255	288	311	131	142,5
9/9-8/9 Tig **	R609A2	298	255	354	311	164	142,5
10/8	R609A3	265	284	321	340	147,5	157
10/10	R609A4	331	284	387	340	180,5	157
12/9	R609A5	309	334	365	390	169,5	182
12/12	R609A6	395	334	451	390	212,5	182
15/11	R609A7	373	397	429	453	201,5	213,5
15/15	R609A8	471	397	527	453	250,5	213,5
18/13	R609A9	430	471	486	527	230	250,5
18/18	R609C0	557	471	613	527	293,5	250,5

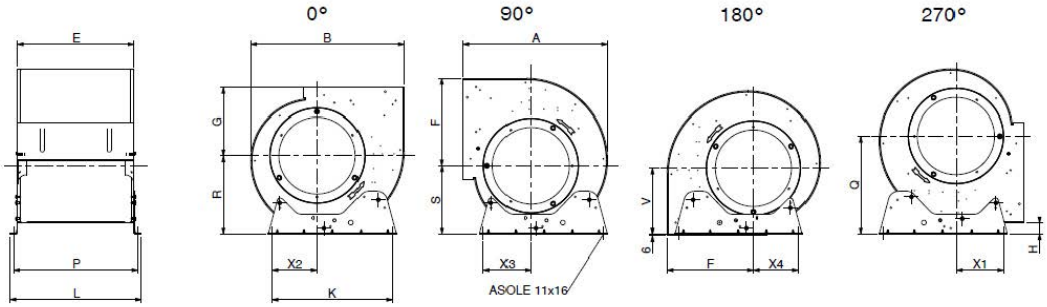
9.5.3 Mounting feet kit

Materials
Galvanized steel accordirng to EN 10346 standard.

Assembly
Fix to the sides by means of self-tapping screws 6,3x12,5 **"3"** (UNI EN ISO 7049:2012), insert the rubber vibration insulators into the holes of the mounting feet **"4"**. The mounting kit contains screws and vibrations insulators.
The feet can be fixed so as to allow the fan to be installed with the scroll orientated to 0°, 90°, 180° and 270°.





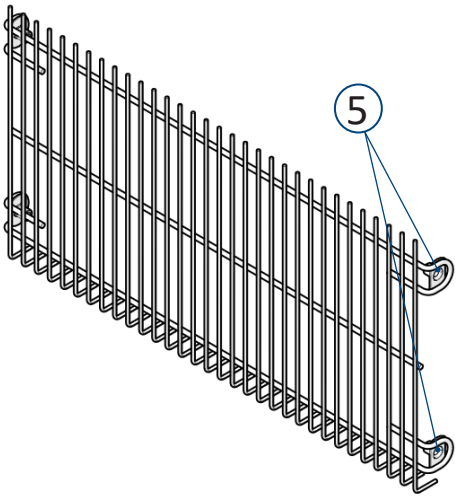


The below mentioned codes are suitable for fans with spiders, bearing supports or motor brackets fixed on the curve part of the inlet cone. For spiders fixed on the flat part of the side plate, please contact the technical dept of **Nicotra Gebhardt**.

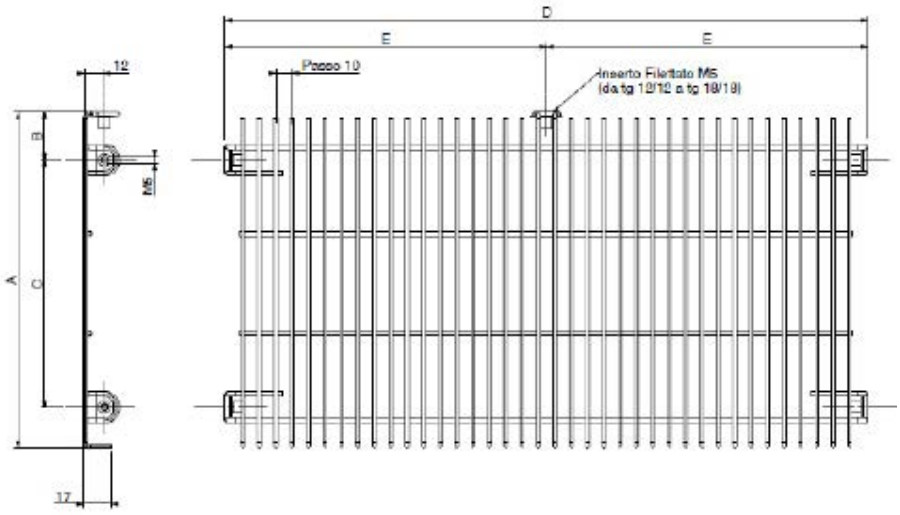
Size	Code	A	B	E	F	G	H	K	L	P	Q	R	S	V	X1	X2	X3	X4
7/7	RA80003ZZ0000000	316	325	232	187	153	17	225	282	258	203	169	145	147	117	86	88	47
7/9	RA80003ZZ0000000	316	325	298	187	153	17	225	348	324	203	169	145	147	117	86	88	47
8/7 Tig	RA80003ZZ0000000	318	326	232	185	155	15	225	282	258	201	169	147	-	120	85,5	95	-
8/9 Tig	RA80003ZZ0000000	318	326	298	185	155	15	225	348	324	201	169	147	-	120	85,5	95	-
9/7	RA80005ZZ0000000	379	387	232	216	185	38	300	282	258	253	199	177	179	119	124	123	120
9/9	RA80005ZZ0000000	379	387	298	216	185	38	300	348	324	253	199	177	179	119	124	123	120
10/8	RA80006ZZ0000000	425	443	265	250	203	38	340	315	291	287	227	198	197	136	132	135	132
10/10	RA80006ZZ0000000	425	443	331	250	203	38	340	381	357	287	227	198	197	136	132	135	132
12/9	RA80008ZZ0000000	491	521	309	295	230	38	408	359	335	332	266	232	224	161	153	161	153
12/12	RA80008ZZ0000000	491	521	395	295	230	38	408	445	421	332	266	232	224	161	153	161	153
15/11	RA8000BZZ0000000	569	609	373	343	264	38	495	423	399	380	309	272	258	197	211	201	200
15/15	RA8000BZZ0000000	569	609	471	343	264	38	495	521	497	380	309	272	258	197	211	201	200
18/13	RA8000CZZ0000000	684	739	430	416	314	42	608	480	456	457	376	340	307	262	283	278	288
18/18	RA8000CZZ0000000	684	739	557	416	314	42	608	607	583	457	376	340	307	262	283	278	288

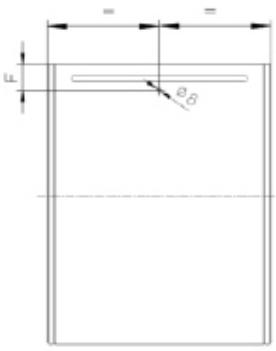
9.5.4 Outlet protection guards

Materials
235 JR steel according to UNI EN 10025
Surface: Fe/Zn 8 according to UNI EN ISO 2081



Assembly
Fix the guards with four M5 screws using the two Ø6 holes **"5"** on each side, located at about 40/45 mm from the external rim.
For sizes between 12/12 and 18/18, the guard can be fixed to the back inserting a fifth M5 thread on a Ø6 hole on the back itself.





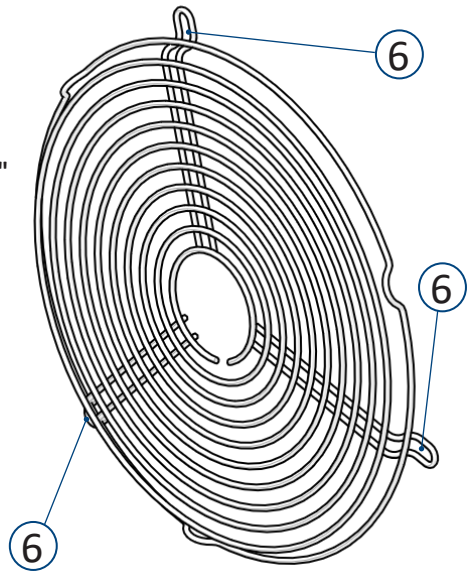
Hole position on the scroll to fix the 5th thread insert (see picture aside).

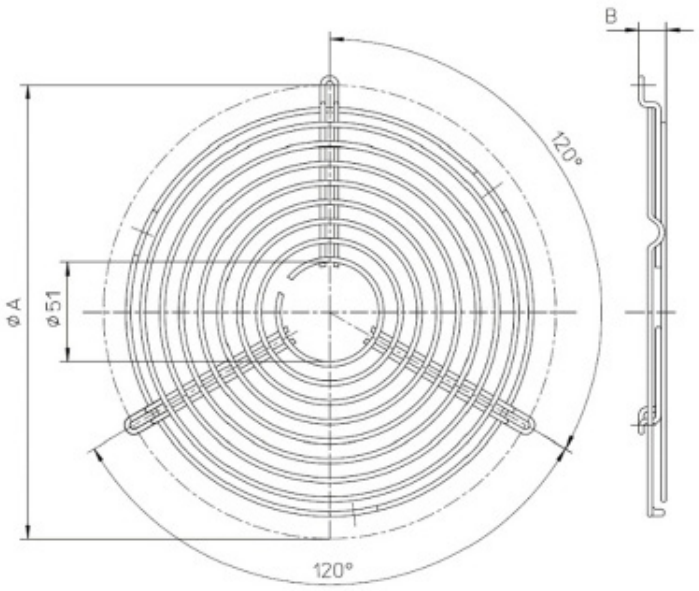
Size	Code	A	B	C	D	E	F
7/7	R722N6	125	25	75	230	-	-
9/7	R722N7	150	25	100	230	-	-
9/9	R722N8	150	25	100	296	-	-
10/8	R722N9	168	25	118	263	-	-
10/10	R722P0	168	25	118	329	-	-
12/9	R722P1	200	25	150	307	-	-
12/12	R722P2	204	29	150	393	196,5	45
15/11	R722P3	241	31	185	371	185,5	45
15/15	R722P4	241	31	185	469	234,5	45
18/13	R722P5	296	31	240	427	213,5	40
18/18	R722P6	296	31	240	554	277	40

9.5.6 Inlet protection guard kit

Materials
235 JR steel according to UNI EN 10025
Surface: Fe/Zn 8 according to UNI EN ISO 2081

Assembly
Fix the protection guards using self-threading screws 3,5 x 9,5 on the 3 Ø2,5 holes **"6"** of the inlet cone.

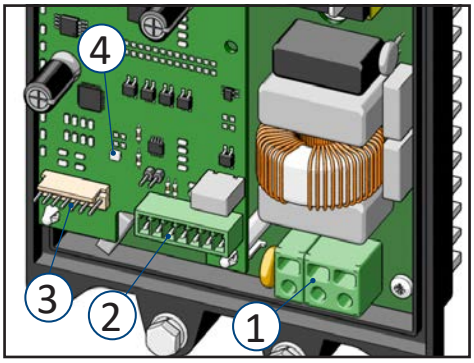


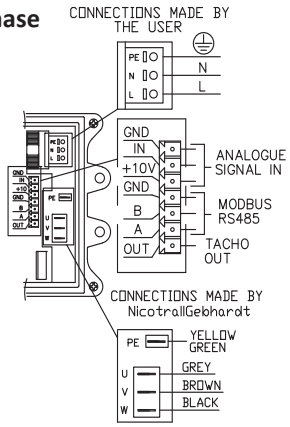


Size	Code	Ø A	B
7/7	689110	194	24
8/7T-8/9T-9/7-9/9	689111	235	14
10/8 - 10/10	689112	264	14

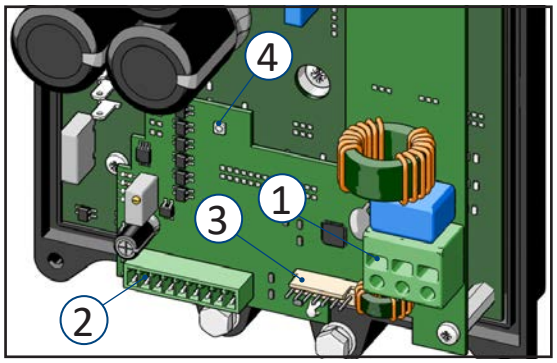
9.6 Electrical connections

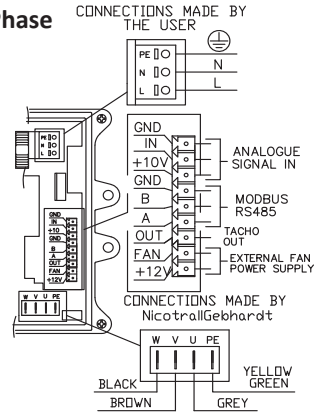
DDMP 1.05kW 1-Phase



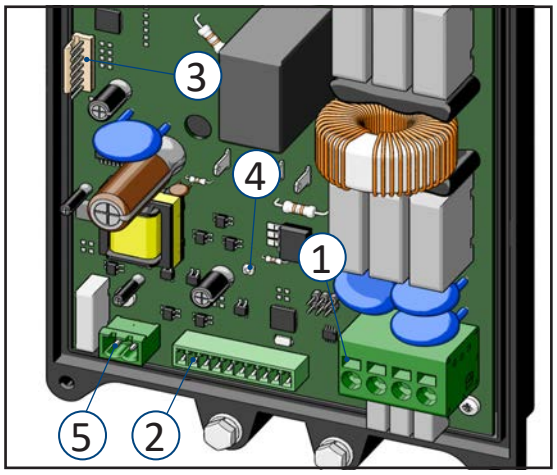


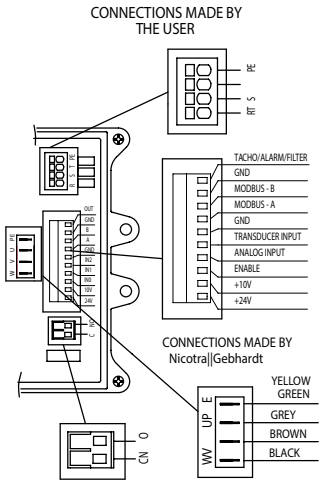
DDMP 2.1kW 1-Phase





DDMP 2.65kW 3-Phase

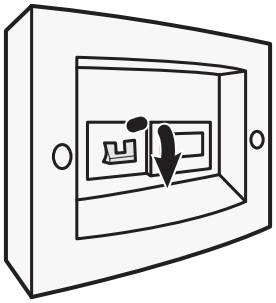




REF.	DESCRIPTION
1	Power supply
2	Control board connection
3	Communication
4	Blinking LED
5	Relay connection

Make sure that a differential switch (circuit breaker) has been installed upstream the line and that it functions properly.

Before carrying out any intervention on the electrical system, disconnect the power supply by means of main switch.



WARNING

Work on the driver/fan by unqualified personnel or failure to comply with warnings can result in severe personal injury or serious damage to material.
Only suitably qualified personnel trained in the set-up, installation, commissioning and operation of the product should carry out work on the driver/fan. This driver must be grounded.
The power supply terminals L, N (1-Phase) or R, S, T (3-Phase) and the motor terminals U, V, W can carry dangerous voltages even if the driver is inoperative.

9.6.1 Power supply

The end user must connect the power supply cable and the command signal to the control board, while the motor connection is already done by **Nicotra Gebhardt**.

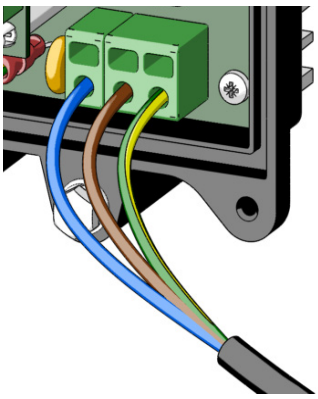
As concerns the cable minimum section, check the requirements issued by the country of installation.

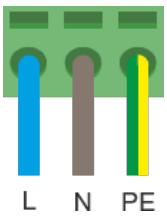
DDMP 1.05kW 1-Phase
Single Phase 220/240V ±10% @ 50/60Hz
The performance in the range [200V-264V] @ 50Hz/60Hz is always the same due to the PFC module inside the driver.

DDMP 2.1kW 1-Phase
Single Phase 220/240V ±10% @ 50/60Hz
The performance in the range [200V-264V] @ 50Hz/60Hz is always the same due to the PFC module inside the driver.

Min. and max. wire section:
Spring-loaded push-in clamp, suitable for
- 0.2 mm² - 24 AWG up to 2.5 mm² - 12 AWG (stranded) or 4 mm² (solid) wire

Use a bladed screwdriver, 0.6x3.5 mm max, to unlock.

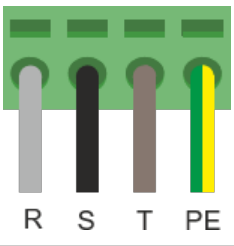


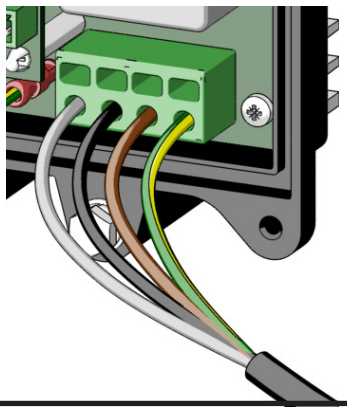


DDMP 2.65kW 3-Phase
Three Phase 400V ±10% @ 50/60Hz
The maximum fan performance, within the nominal range of supply-voltage [360-440V], may be sensitive to the actual supply voltage. Whether the fan maximum speed is related to the supply voltage depends on the fan size and duty point.

Min. and max. wire section:
Spring-loaded push-in clamp, suitable for
- 0.2 mm² - 24 AWG up to 6 mm² - 8 AWG (stranded) or 10 mm² (solid) wire

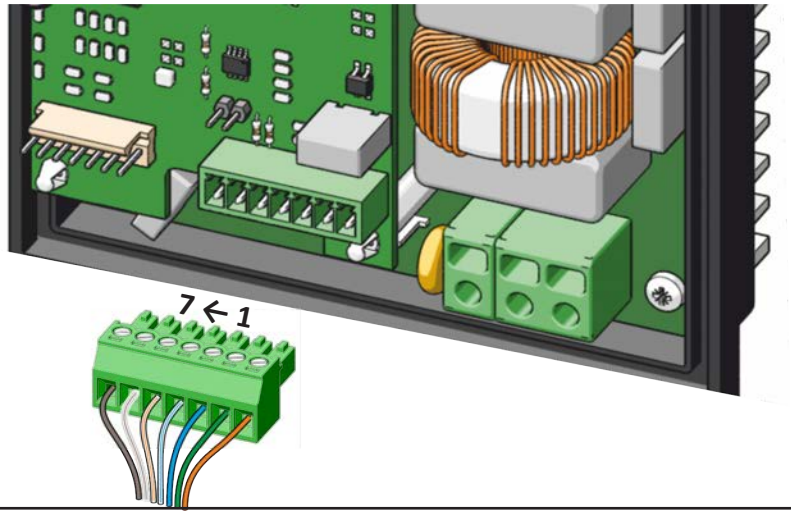
Use a bladed screwdriver, 0.6x3.5 mm max, to unlock.

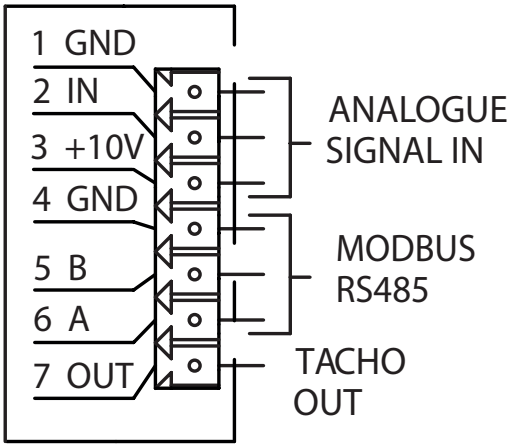




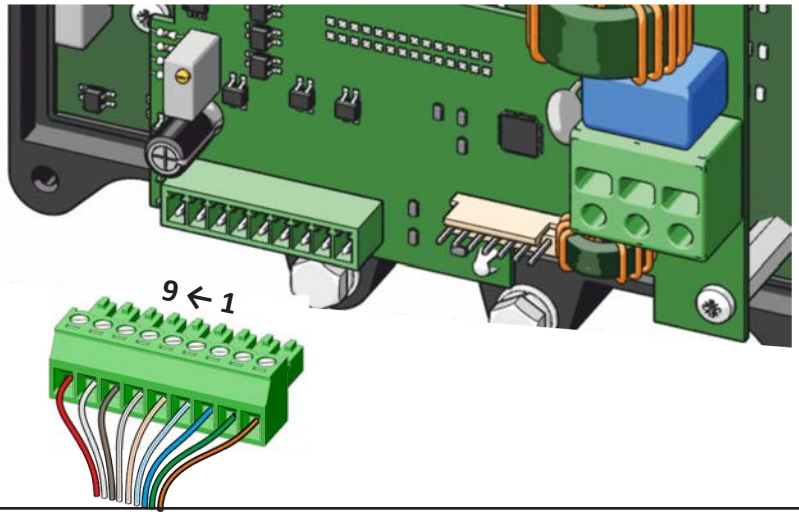
9.6.2 Control board connection

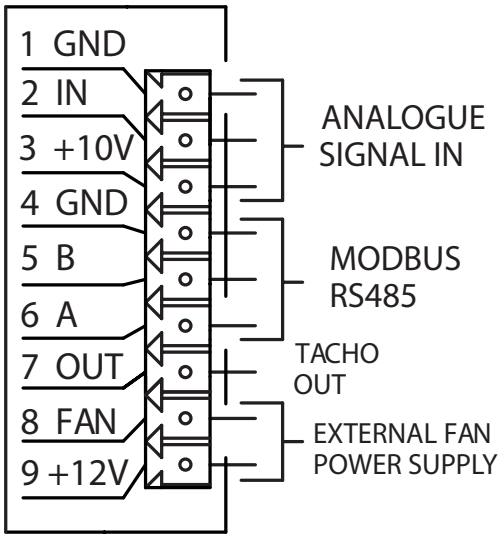
DDMP 1.05kW 1-Phase



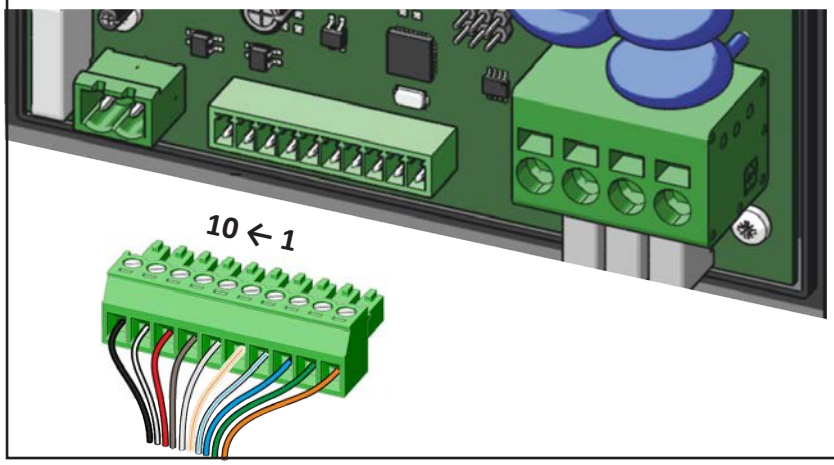


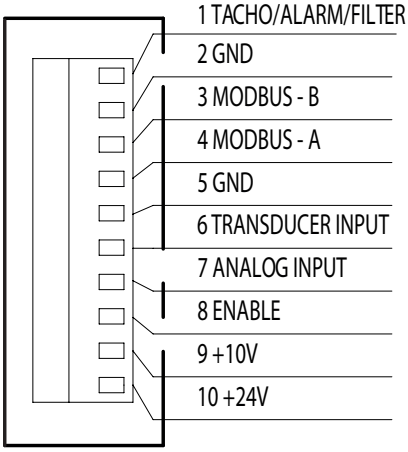
DDMP 2.1kW 1-Phase





DDMP 2.65kW 3-Phase





Min. and max. section:

- 0.13 - 1.31 mm² (26 - 16 AWG) solid or stranded cable.

⚠ WARNING

Do not reverse the input signal or connect the +10V, 12V or +24V to signal ground. The driver could be damaged.
Do not apply signals with voltage outside the indicated limits, the driver could be damaged.

9.6.3 Connection details

In this paragraph are explained the feature and the possible connection of the control board.
The control board terminals are opto-insulated.

The available features can be different depending on the fan model.

9.6.3.1 Analog

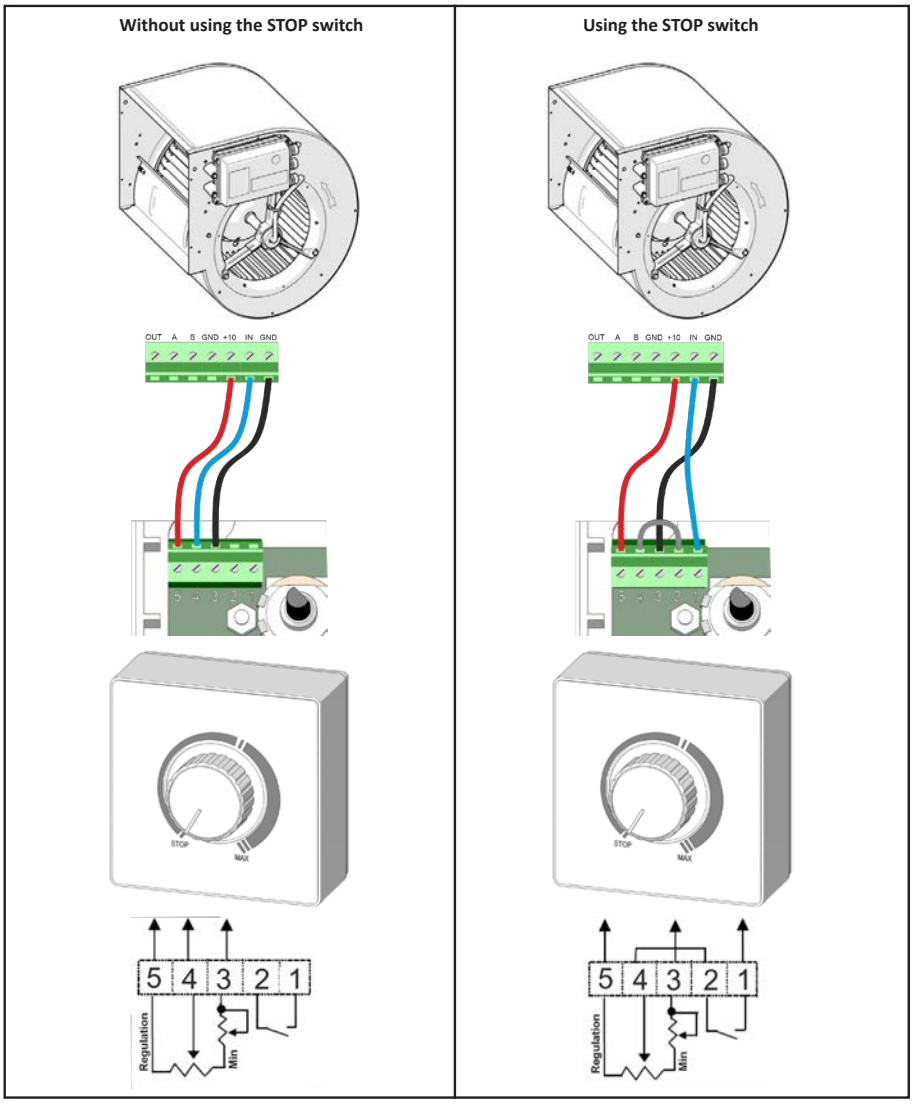
This is the driver default mode and the signal must be connected into the ANALOG INPUT and the reference to GND.
The analog input can accept also a PWM signal with f>1kHz.

With 3-phase drivers, a jumper or a switch is needed between 10 or 24 V and Enable to start the fan. See also paragraphs 9.6.3.3 and 13.3.

⚠ WARNING

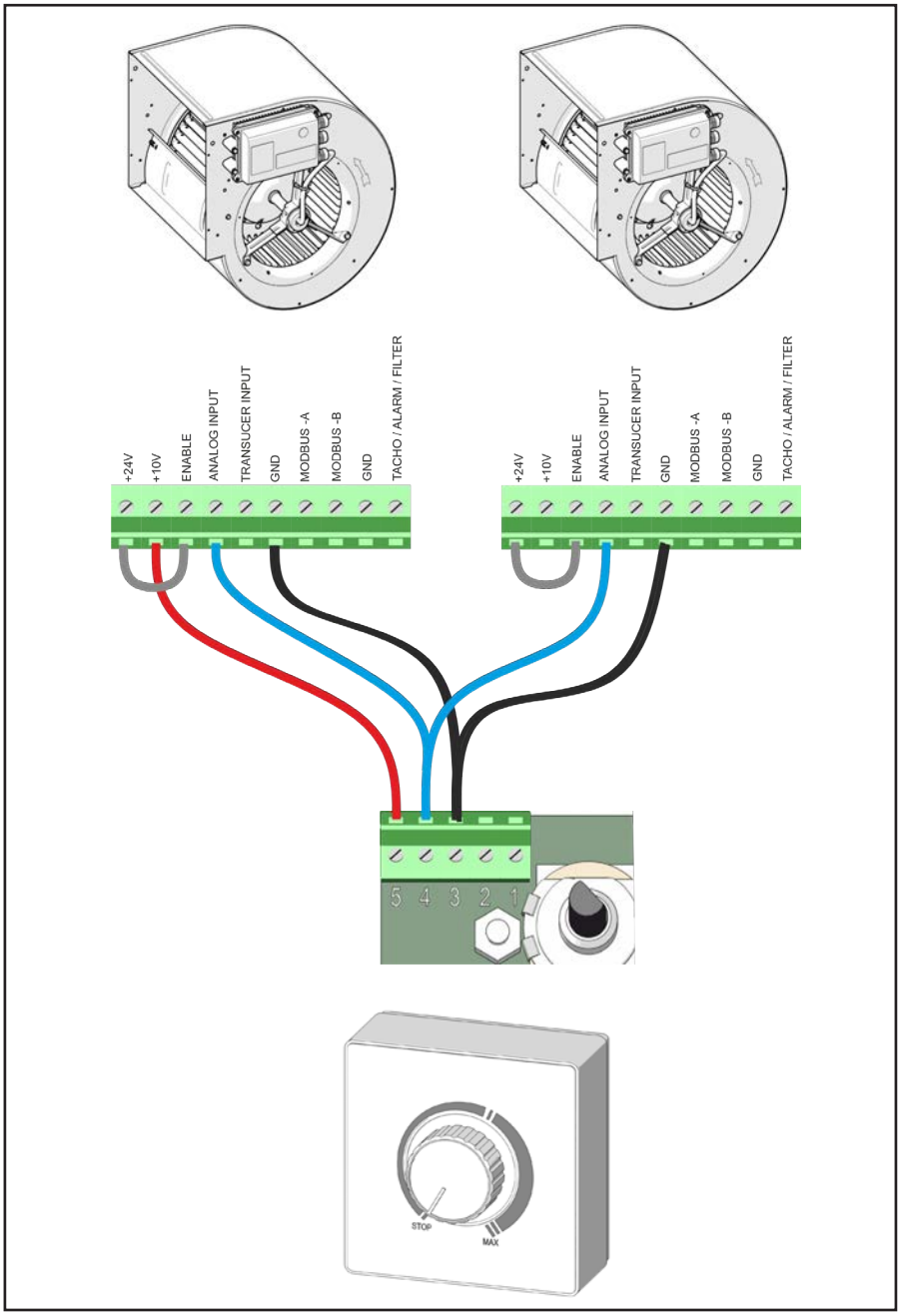
Do not use devices having the signal GND connected to the NEUTRAL cable of the power supply. The driver may be damaged or not functioning properly.

The available +10V power supply of the driver is intended to be used with a potentiometer of minimum 2KOhm, with a max absorbed current of 5mA.
Any different devices connected to it could bring to an undesired functioning of the driver or of connected device.
Nicotra Gebhardt can provide a dedicated potentiometer: REGPOT code K43138.

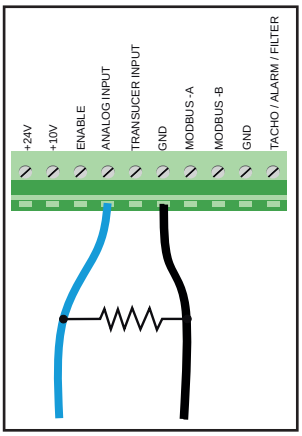


If two or more fans are installed in the same compartment and operated in parallel, the fans must start and stop at the same time.

An auto-restarting alarm occurs when a fan is forced to run forward (or backward) rotation with a speed higher than 150 rpm.



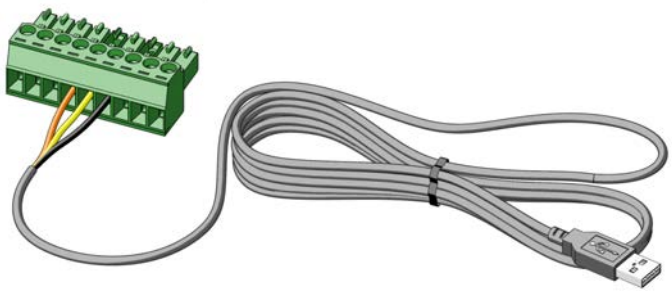
If an ext. 4-20mA device is used, it is necessary to add 0.1% precision resistances between the ANALOG INPUT and GND.
The value of the resistance can range from:
125 Ω -> V_{signal} ranges from 0.5V to 2.5V
to 500 Ω -> V_{signal} ranges from 2V to 10V

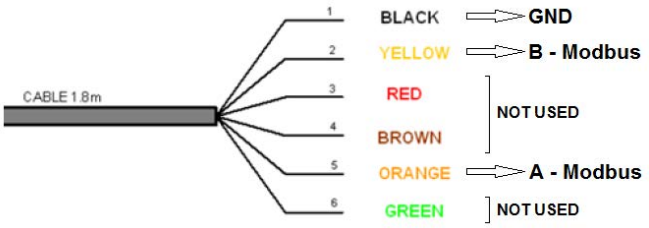


9.6.3.2 Modbus Communication

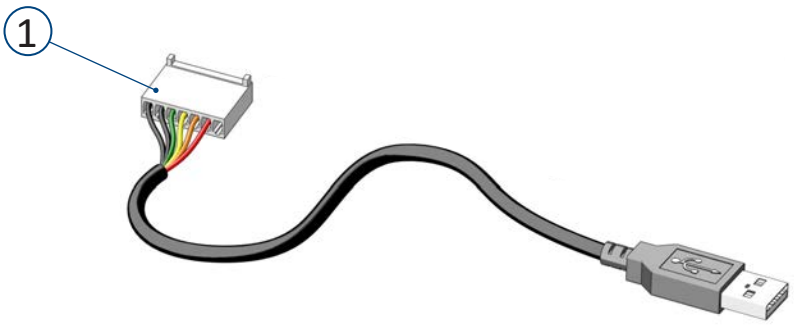
A Modbus RTU protocol is available on all the fan models.
The line must be connected to MODBUS-A, MODBUS-B and GND pins.
There are two possible Modbus connections:
1) During the fan functioning through any RS-485 serial connection
2) With the driver powered off through an UART serial connection

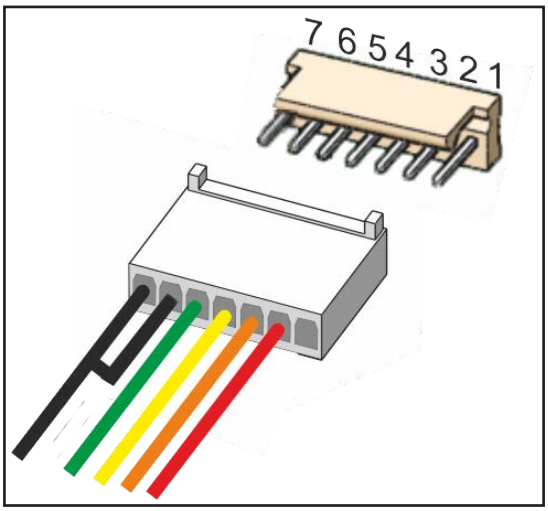
To connect the driver to a PC during the fan functioning, a USB to 485 converter can be used: K431F8.



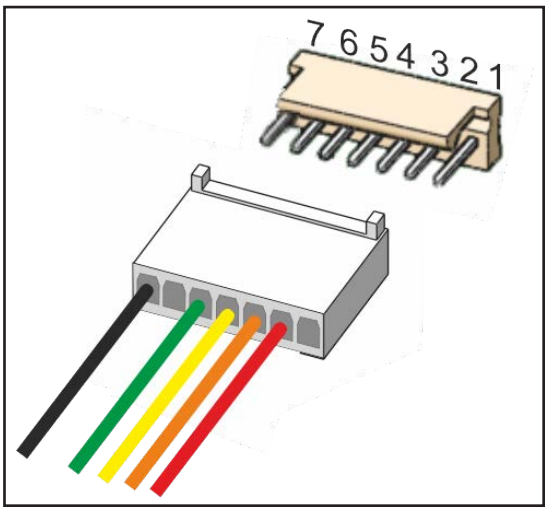


To connect OFFLINE the driver to a PC when the fan is powered off, a USB to UART converter can be used: K431A6 for 1-phase drivers and K431F7 for 3-phase drivers.
A MOLEX connector **"1"** is used to connect the cable to the driver.





1-phase



3-phase

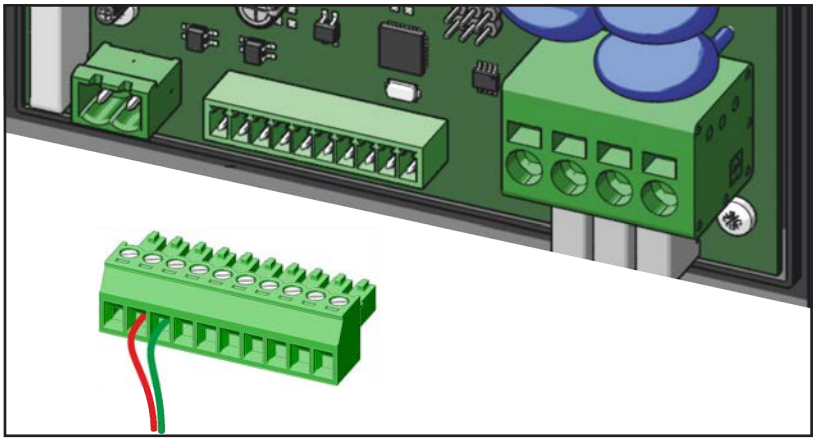
Specifications and drivers can be downloaded from Nicotra Gebhardt website: https://www.nicotra-gebhardt.com

9.6.3.3 Enable Signal [for DDMP 2.65kW - 3-Ph only]

The fan runs when the ENABLE input is bridged to the +10V or +24V power supply.

The status of the ENABLE input does not affect the Modbus Temporary modes.

If it is not necessary turning on/off the fan with an external switch, a jumper can be inserted between clamps +24V and ENABLE. In case this jumper is not included, the fan will not start.
For further details, refer to par. 13.3.

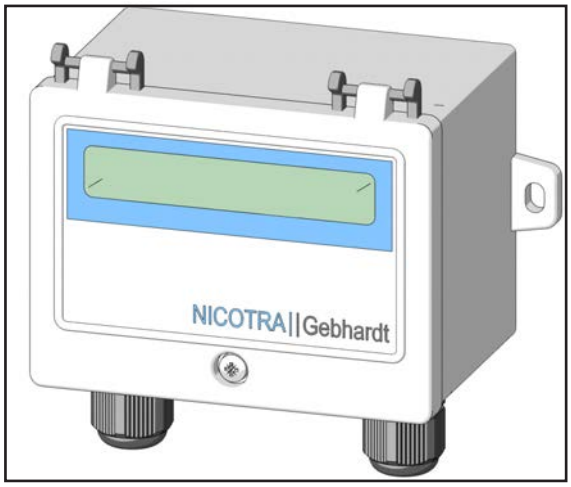


9.6.3.4 Pressure and flow meter [for DDMP 2.65kW - 3-Ph only]

To control the airflow for reaching the desired value, it is recommended using the suitable operating mode "Constant airflow" of the power and control system incorporated into the fan (see par. 10.2). This system allows controlling the airflow only by measuring the electrical parameters of the motor power supply, by enabling a specific driver operating mode without installing additional components.

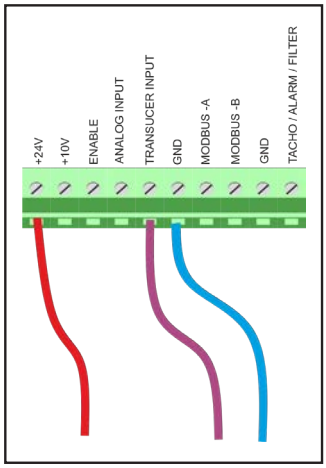
As an alternative to this operating mode, it is possible to install the airflow measuring and adjusting system (see picture aside), which is composed of pressure tapping block W89041 connected to transducer K43198 by means of K409A2 piping. This transducer is connected to the PID regulator incorporated into the driver, which is installed on the fan.

For a correct installation, follow the instructions supplied with the single components.

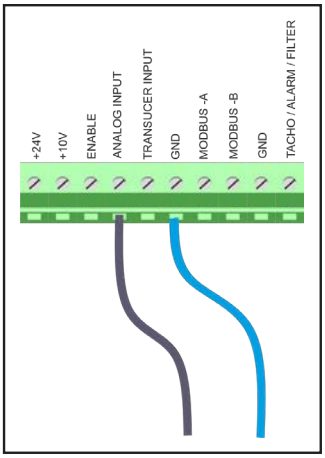


An external transducer can be powered and connected to the driver.
There are two possible connections depending on the kind of transducer used:
1) Open Control Loop Transducer
2) Closed Control Loop Transducer
Nicotra Gebhardt can provide a Pressure Transducer code K43198 that can work both in open and closed loop.

If the transducer does not have its own control and it supplies a voltage signal [0, +10V] proportional to the measured variable, it is possible to use the tunable PID of the driver.
The signal must be connected to the TRANSDUCER INPUT.

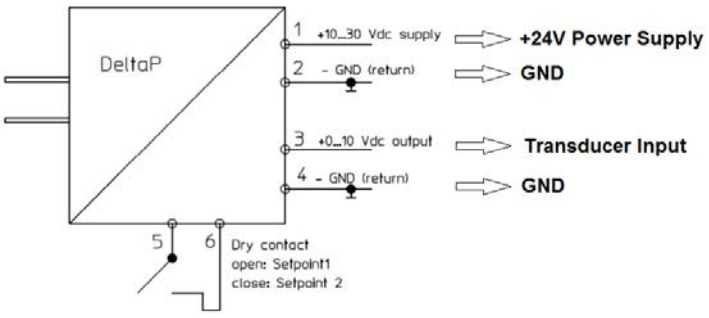


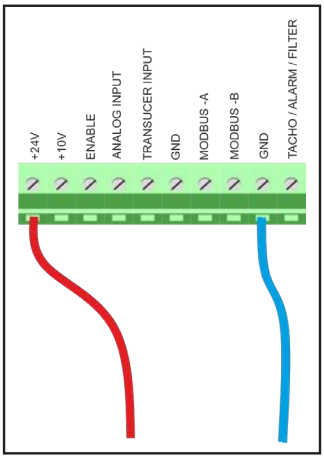
If the transducer has its own PID control, the signal must be connected to the standard ANALOG INPUT.



9.6.3.5 +24V AUX Power supply [for DDMP 2.65kW - 3-Ph only]

The +24V output can supply a max current of 50mA and it is able to drive the **Nicotra Gebhardt** pressure transducer (code K43198).
Use an available ground pin on the board for powering devices.

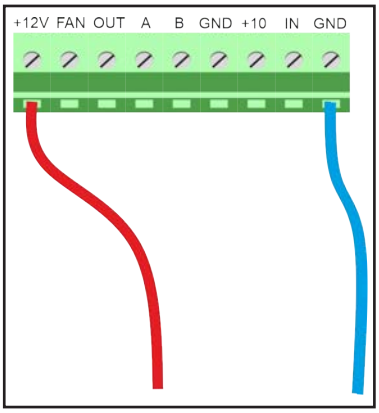




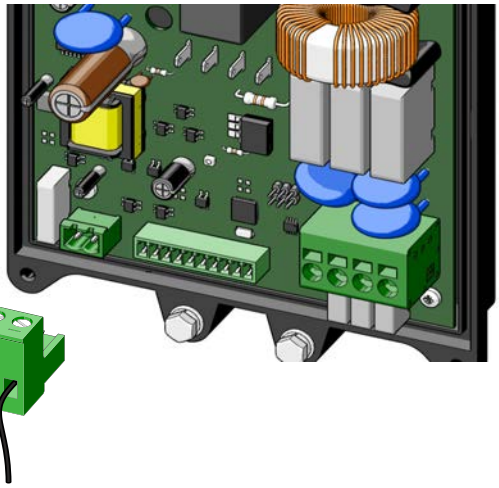
9.6.3.6 +12V AUX Power supply [for DDMP 2.1kW - 1-Ph only]

The 12V power supply can be used to provide power to the pressure transducer K43198, where a 24V supply is not available.
An auxiliary power supply of 12V is available on the 2.1kW Single-Phase drivers.
The max current absorbed must be lower than 200mA.
Use an available ground pin on the board for powering devices.

This power is not stabilized and it decreases when the current absorption exceeds the above indicated limit.
The FAN pin is not active.



9.6.3.7 Relay [for DDMP 2.65kW - 3-Ph only]



A relay is available on the Three-Phase drivers.
It is suitable for 250Vac/30Vdc 5A.

When the driver is powered off the relay is open -> the PCB label indicates C-NO.
During the functioning the relay is Normally Closed in No-Alarm condition and open in case of alarm.

Min. and max. section:

- 0.33 - 2 mm^2 (22 - 14 AWG) solid or stranded cable.

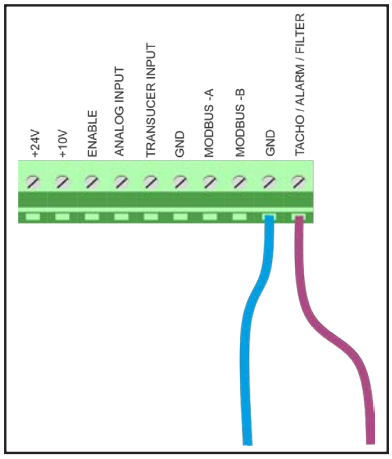
9.6.3.8 Tachometric, Alarm and Filter Output

The analogue output channel is configured, by default, to provide a tachometric output signal.

The tachometric output is a 0 to 5V PWM waveform at 1KHz (for DDMP 1.05kW -1-Ph only).
The tachometric output is a 0 to 10V PWM waveform at 1KHz (for all other fans).

$$\text{Duty Cycle (Speed)} = 10\% + \frac{90\% \cdot (\text{Speed}_{\text{Real}} - \text{Speed}_{\text{min}})}{\text{Speed}_{\text{MAX}} - \text{Speed}_{\text{min}}}$$

when the speed is equal or higher than the speed min and it is 0% when the speed is lower.
The device reading the output must be connected to TACHO\ALARM\FILTER pin and GND.
The max current supplied of the output is 0.2mA.



Remember that the $Speed_{Real}$ is 0 whenever the required speed is lower than $Speed_{min}$ unless the fan is in the dragging phase.

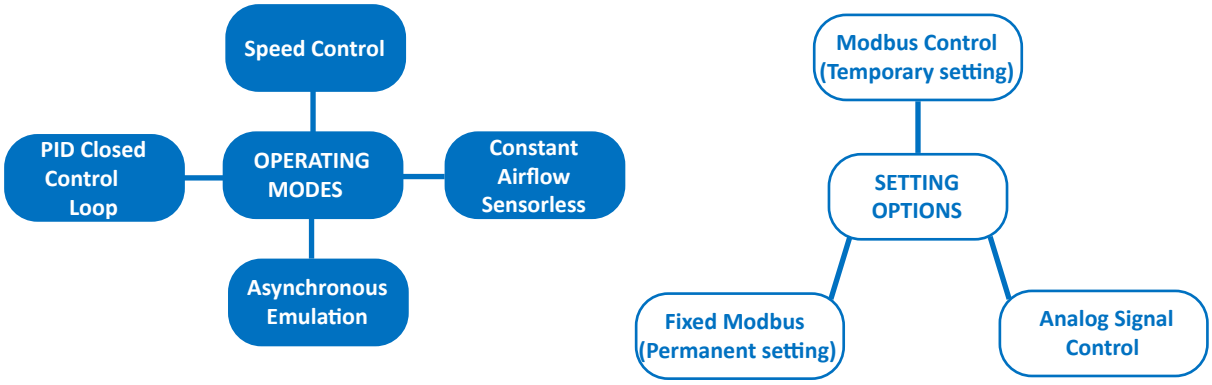
The same analogue output channel can be reconfigured, by changing the value in Holding Register 46 (see paragraph 17.3 at page 54), as a Digital Alarm Output (refer to chapter 18 and paragraph 18.4), or in one of the alternative alarm modes described in paragraphs 11.1 and 11.2.

9.6.3.9 Input Impedances

Input Impedances		**Feature available on**
ANALOG INPUT	20 kΩ	DDMP 1.05 kW 1-Phase
ANALOG INPUT	200 kΩ	DDMP 2.1 kW 1-Phase
ENABLE ANALOG INPUT TRANSDUCER INPUT	200 kΩ	DDMP 2.65 kW 3-Phase

10. OPERATING MODES AND SETTING OPTIONS

Depending on the fan model, there are 4 possible **Operating Modes** and for each mode 3 possible **Setting Options**.



The operating modes and the setting options can be chosen by modifying the INPUT TYPE **Holding Register 34**.

10.1 Speed control

10.1.1 Analog speed control

(INPUT TYPE = 1 Default factory setting)
Through this setting the fan speed is proportional to the analog voltage input. The fan speed is limited by the Safe Operating Area, therefore, depending on the fan working point, the fan could be no more able to increase the speed coherently to the set voltage value.
To avoid the loss of signal dynamic, a speed limit rescaling is necessary by modifying the value of the Max Speed **Holding Register 2**. It is also possible to rescale the min Speed by modifying the **Holding Register 1**.
The analog signal can be read from the **Input Register 14**.

For more details refer to the ANNEX -> Analog Signal Considerations.

The MAX and min speed default values are in function of the fan sizes.

The relationship between control voltage and fan speed is described in paragraph 10.1.4 and, with more detail, in chapter 1 of the Technical Annex to this manual.

10.1.2 Modbus temporary speed control

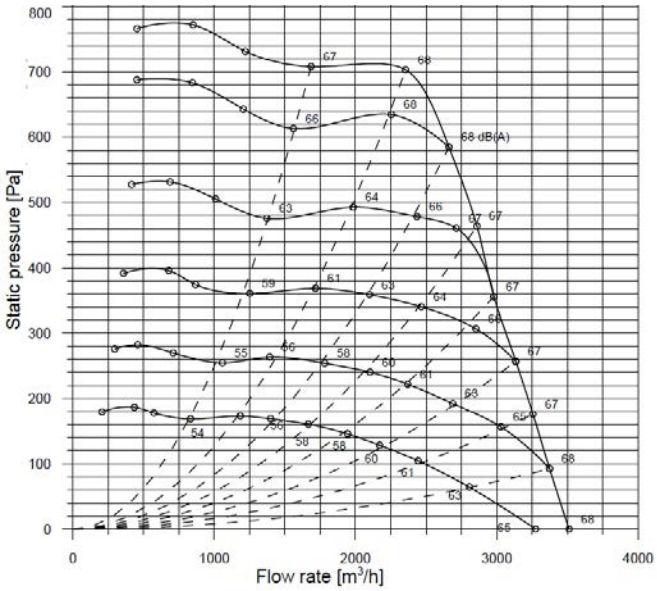
(INPUT TYPE = 0)
Through this setting the fan runs at the speed defined by modifying the **Holding Register 66**.
The setting is maintained meanwhile the fan is powered on and it is lost when the fan is powered off.

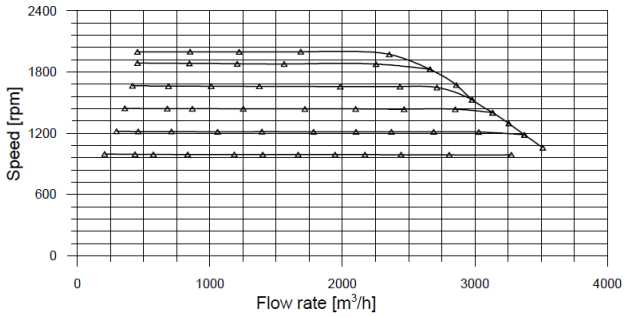
10.1.3 Modbus fixed speed control

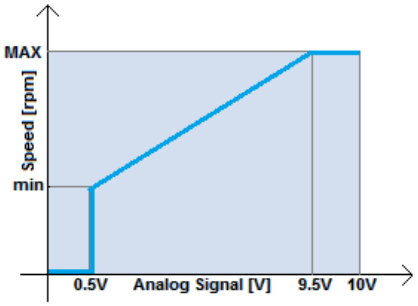
(INPUT TYPE = 2)
Through this setting the fan runs at the speed defined by modifying the **Holding Register 21**.
The setting is permanent and fan starts at the defined speed each time it is powered on.

10.1.4 Speed control curves: example

The following figures show a set of performance curves at different speed settings limited by the fan max working limit curve (see paragraph 1.6).







10.2 Constant airflow

10.2.1 Analog constant airflow

(INPUT TYPE = 4)
Through this setting the constant airflow is proportional to the analog voltage input.
Each fan has default lower and higher limit for the constant airflow curves that can be increased by modifying the **Holding Register 42** and the **Holding Register 43**.
The choice of reducing the Constant Airflow Range is depending on the user application and it is especially useful when the application must guarantee a defined minimum constant airflow.
The selectable airflows are restricted to a minimum and/or maximum defined range for each fan size.
The lower limit avoids big deviations from the constant airflow while the high limits are determined by the Safe Operating Area.

10.2.2 Modbus temporary constant airflow

(INPUT TYPE = 5)
Through this setting the fan runs at the constant airflow defined by modifying the **Holding Register 66**.
The setting is maintained meanwhile the fan is powered on and it is lost when the fan is powered off.

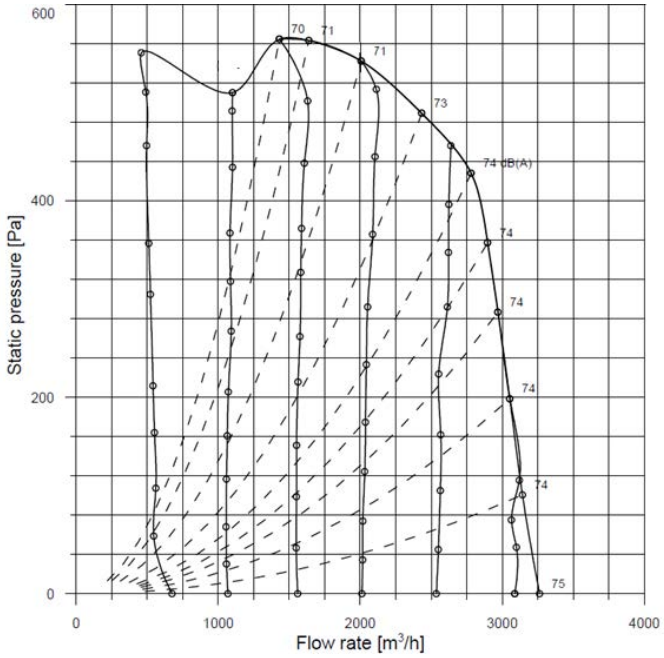
10.2.3 Modbus fixed constant airflow

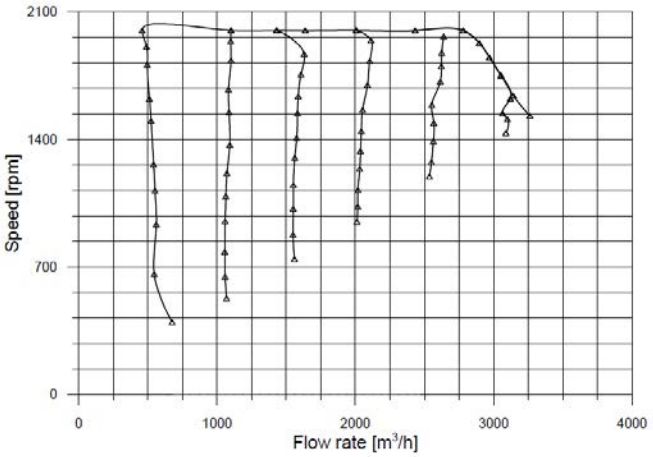
(INPUT TYPE = 5)
Through this setting the fan runs at the constant airflow defined by modifying the **Holding Register 39**.
The setting is permanent and fan starts at the defined constant airflow each time it is powered on.

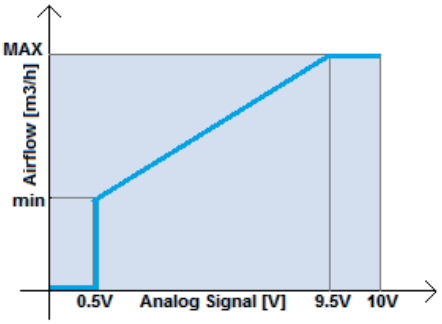
The driver microcontroller elaborates only speed and current data to obtain the constant performance, but it cannot recognize airflow and static pressure values. Therefore, these values are not available in the driver Input Registers. The max resolution from on constant airflow to another is +/-50m3/h. The max precision guaranteed is SET AIRFLOW +/- 100 m3/h. In the instability areas typical of some fan sizes the constant airflow precision can't be guaranteed. It's anyway suggested to work outside these areas.

10.2.4 Constant airflow curves: example

The following figures show 6 constant airflow curves randomly chosen and the relationship between the voltage signal and the corresponding airflow.







10.3 Asynchronous emulation

Through this mode there is the possibility to emulate the behavior of an asynchronous induction motor with a slip and a power limitation dependent on the load and speed (therefore there could be some differences from each size). The control is expressed in percentage instead of a defined measure unit. The lower is the slip the higher is the performance and vice versa.

10.3.1 Analog asynchronous emulation

(INPUT TYPE = 7)
Through this setting the slip is proportional to the analog voltage.

10.3.2 Modbus temporary asynchronous emulation

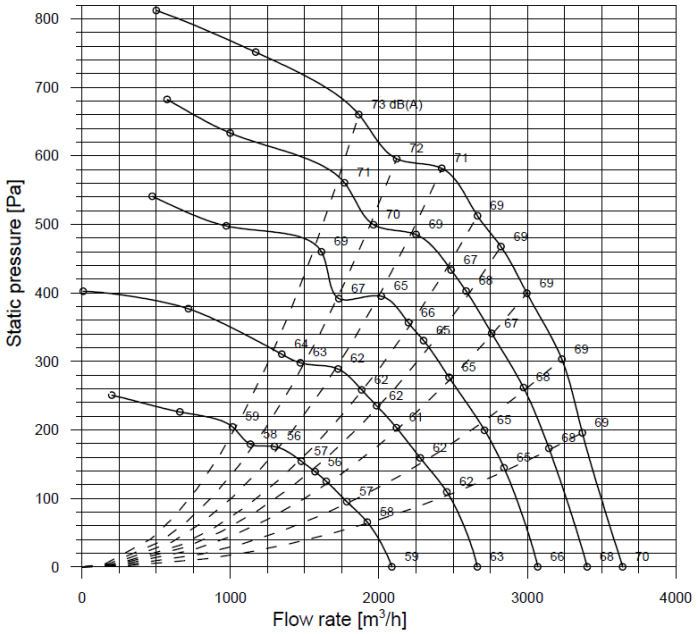
(INPUT TYPE = 8)
Through this setting the fan emulates an ACIM motor and the slip is defined by modifying the **Holding Register 66**.
The setting is maintained meanwhile the fan is powered on and it is lost when the fan is powered off.

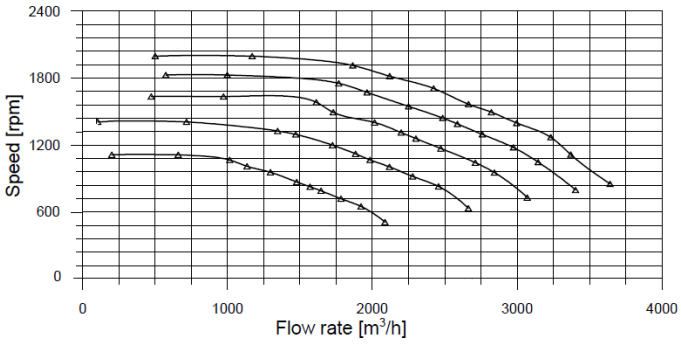
10.3.3 Modbus fixed asynchronous emulation

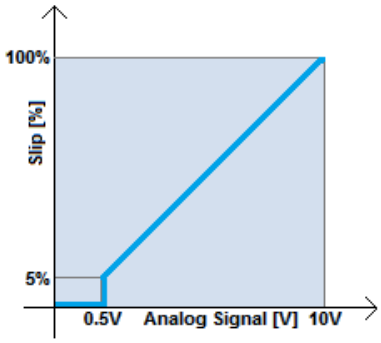
(INPUT TYPE = 9)
Through this setting the fan emulates an ACIM motor and the slip is defined by modifying the **Holding Register 30**.
The setting is permanent and fan starts at the defined constant slip each time it is powered on.

10.3.4 Asynchronous emulation curves: example

The following figures show 5 curves with the following slip percentage: 100%, 80%, 60%, 40% and 20%.







The slip has not a physical meaning and must be intended as a 100% full performance and 0% fan stop.

10.4 PID closed control loop

Through this setting the fan can work in a PID closed control loop where the measured process variable is connected to the TRANSDUCER INPUT that can be monitored through the **Input Register 31**.
and it must be in the range of [0,10V]. The PID mode can be therefore used with temperature probes, pressure transducer, CO/CO2 detectors, etc.

The parameters to set are:
- K_P = Proportional Gain -> **Holding Register 51**
- K_I = Integral Gain -> **Holding Register 52**
- K_D = Derivative Gain -> **Holding Register 53**
- Time = T_{PID} -> **Holding Register 54**

The following equations represent the simplified PID code:

$$E_{rror}(n) = \left(R_{eference} - M_{easure}\right)$$

$$P_{roportional} = K_P \cdot E_{rror}(n)$$

$$I_{ntegral}(n) = I_{ntegral}(n-1) + K_I \cdot E_{rror}(n) \cdot T_{PID}$$

$$D_{erivative} = \frac{K_D \cdot \left(E_{rror}(n) - E_{rror}(n-1)\right)}{T_{PID}}$$

$$E_{rror}(n-1) = E_{rror}(n)$$

$$I_{ntegral}(n-1) = I_{ntegral}(n)$$

$$C_{ontrol} = P_{roportional} + I_{ntegral}(n) + D_{erivative}$$

Chapter 5 of the technical Annex to this manual describes a practical procedure to calibrate the PID constants, to achieve stable operation of the closed-loop PID control system.

As an alternative, the Nicotra Gebhardt Fan Configurator software for PC is also including an automatic procedure to calibrate the PID controller. In many cases, this software function can save the user from a lengthy manual calibration procedure. For further information, refer to the Fan Configurator manual.

10.4.1 Analog ref. PID closed control loop [for 3-phase only]

(INPUT TYPE = 10)
In this mode the PID reference is given by the analog signal present at the ANALOG INPUT that can be monitored through the **Input Register 29**.

10.4.2 Modbus temporary ref. PID closed control loop

(INPUT TYPE = 11)
In this mode the PID reference is defined by modifying the **Holding Register 66**.
The value of the reference is expressed in steps of 0.1 Volt (therefore the register ranges from 0 to 100) The PID error is calculated in the following way:

Error = ($Modbus_{REG\_66}$ - $ANALOG_{Input}$)

10.4.3 Modbus fixed ref. PID closed control loop

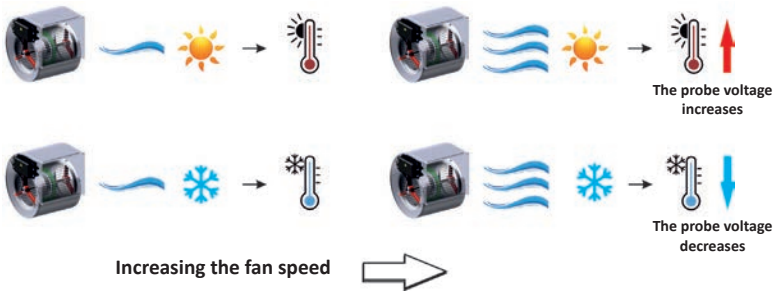
(INPUT TYPE = 11)
In this mode the PID reference is defined by modifying the **Holding Register 50**.
The value of the reference is expressed in steps of 0.1 Volt (therefore the register ranges from 0 to 100) The PID error is calculated in the following way:

Error = ($Modbus_{REG\_50}$ - $ANALOG_{Input}$)

10.4.4 Modbus positive/negative feedback

Depending on the application it could be necessary to invert the feedback behavior.
Through the **Holding Register 31** it is possible to multiply by -1 the PID error.

When the register is set to 0 -> Error = ($R_{eference}$ - M_{easure});
When the register is set to 1 -> Error = (M_{easure} - $R_{eference}$).



10.5 Changing the operation mode

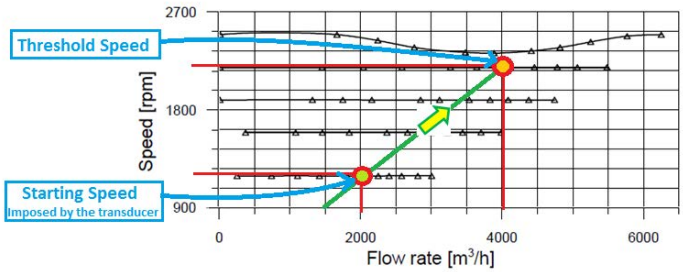
Here are shown the actions passing from one operation mode to another one.

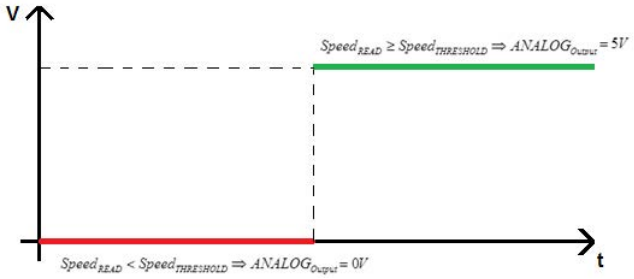
ACTION	ACTIONS A	ACTIONS B
Temporary Setting -> Fixed Setting	The fan must follow the target corresponding to the value stored the related register.	Fan is put in stop mode and after the data are saved the fan follows the target corresponding to the value stored into the related register.
Fixed Setting -> Temporary Setting	The fan must stop waiting for a new register 66 value.	The fan must stop waiting for a new register 66 value.
Temporary Setting -> Analog Signal	The fan must follow the target corresponding to the analog value at the inputs.	Fan is put in stop mode and after the data are saved the fan follows the target corresponding to the analog value.
Analog Signal -> Temporary Setting	The fan must stop waiting for a new register 66 value.	The fan must stop waiting for a new register 66 value.
Fixed Setting -> Analog Signal	The fan must follow the target corresponding to the analog value at the inputs.	Fan is put in stop mode and after the data are saved the fan follows the target corresponding to the analog value.
Analog Signal -> Fixed Setting	The fan must follow the target corresponding to the value stored the related register.	Fan is put in stop mode and after the data are saved the fan follows the target corresponding to the value stored into the related register.

11. OTHER FEATURES

11.1 Filter alarm

This feature is useful when the speed of the fan is not directly set by the user as fans set in Constant Airflow Asynchronous Emulation or PID mode.
The alarm is active when a speed threshold is overtaken (5V or 10V depending on the fan model).

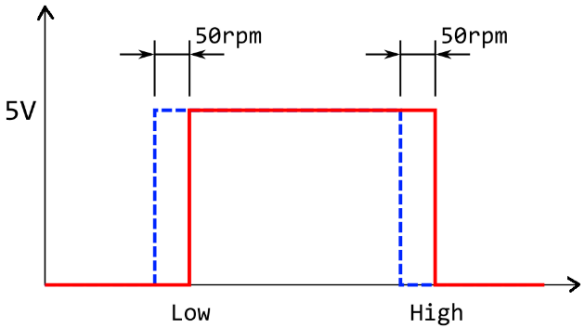




To activate this feature, the **Holding Register 46** must be set at value 2 and the required Speed Threshold value must be set into the **Holding Register 55**. The digital output of the driver changes its status (see above figure).

11.2 Out of functioning range alarm [for 1-phase - 1.05 kW only]

The digital output of the driver is high when the low limit of the speed threshold is overtaken, and it returns low when the high limit of the speed threshold is overtaken.



To activate this feature, the **Holding Register 46** must be set at value 3 and the low value of the Speed Threshold must be set into the **Holding Register 16**.
While the high value of the Speed Threshold must be set into the **Holding Register 55**. The digital output of the driver changes its status following the behavior of the above figure (a hysteresis of 50 rpm is present to avoid several output changes of status).

11.3 Flying start [for 3-phase only]

The algorithm can catch the position of the rotor after changing the target speed to 0 and to a new value in short time. If too long time passed and the fan runs at very low speed, it is not possible to catch the speed: the fan brakes and restarts.

11.4 Regeneration [for 3-phase only]

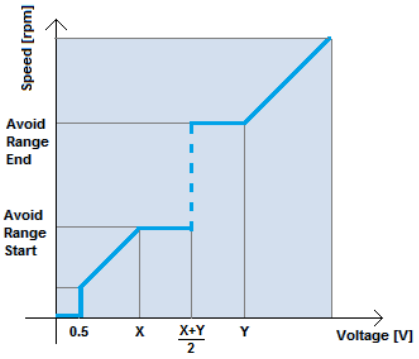
The algorithm can catch the position of the rotor after powering OFF and then ON the fan. If too long time passed and the fan runs at very low speed it is not possible to catch the speed and the fan brakes and restarts.

11.5 Skip speed Range [for 3-phase only]

This feature allows to skip the resonance frequencies of the fan installation.
To activate this feature the Holding Register 32 must be set at the desired Avoid Range Start and the **Holding Register 33** the desired Avoid Range End.

$$Speed_{SET} \leq \frac{AR_{Start} - AR_{End}}{2} \Rightarrow Speed_{target} = AR_{Start}$$

$$Speed_{SET} > \frac{AR_{Start} - AR_{End}}{2} \Rightarrow Speed_{target} = AR_{End}$$

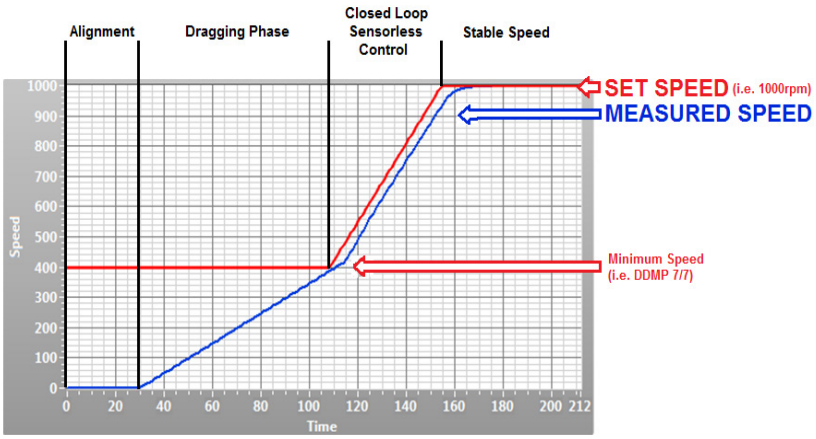


This function should be avoided when used in close control loops application or unstable conditions of the fan could occur.

11.6 Soft start

In the following paragraph the starting phase of a fan is shown.

- The first phase when the fan receives a command to start running is the ALIGNMENT. During this phase the driver aligns the rotor.
- The second phase is the dragging phase, where the fan gradually increases its speed to the minimum in open loop. In this phase the current and speed values present in the Input Register can't be taken in consideration.
- The last phase is the closed loop where the sensorless control is active and from the minimum speed to the target speed the fan accelerates with different ramps basing on the fan size and the wheel inertia. The acceleration and deceleration values are different and to avoid overvoltage alarm or loss of synchronism alarm, the deceleration is always lower.



During the ALIGNMENT and DRAGGING phases a Loss of Synchronism alarm could occur if there is a condition of wrong rotor starting position or wrong position estimation during the open loop phase. This is not a blocking alarm; therefore the fan stops and auto-restarts after few seconds.

12. SOA LIMITATIONS

12.1 Speed limitation

The speed limits can be adjusted for the signal rescaling, but also to limit the noise in the final application.
The **Input Register 2** indicates the Speed Reference (minimum speed during alignment and dragging and the Set Speed in Closed Control Loop). The **Input Register 3** indicates the Measured Speed.

12.2 Power limitation

The driver is set by factory default to the max achievable electrical input power to the driver depending on the model. During the functioning it is possible to monitor the power absorption by reading the **Input Register 31**. If for some application it is necessary to keep the absorption of the fan below a defined power value, it is possible to reduce the max power out by modifying the **Holding Register 36**.

12.3 Output current limitation

The drivers are set by factory default to the max peak current out that changes depending on the motor windings characteristics. During the functioning it is possible to read the peak motor current to the motor by reading the **Input Register 12**.
It is possible to reduce the motor current by modifying the **Holding Register 7**. It is suggested to keep the motor current above 3500mA.

12.4 Input current limitation

This feature is not available for DDMPs.

13. OTHER VARIABLES

There are other variables that can be monitored for a safe use of the fan.

13.1 Bus voltage

The BUS voltage is the DC voltage on the bus capacitors. The driver is continuously monitoring this voltage and will stop the motor in the event of under-voltage or over-voltage.
The value can be monitored through the **Input Register 9**.

13.2 Motor voltage

The motor voltage is the peak value of the phase voltage module. To know the rms line to line value, it must be multiplied by √3/2.
The value can be monitored through the **Input Register 13**.

13.3 Enable Function [for 3-phase only]

A safety enable function is available and it is active for the Operating Modes in the following table.
The value can be monitored through the **Input Register 28**.

Input type	Enable function
0	Not active
1	Active
2	Active
3	Active
4	Active
5	Not active
6	Active

Input type	Enable function
7	Active
8	Not active
9	Active
10	Active
11	Not active
12	Active

14. DERATING AND OVERHEATING PROTECTIONS

14.1 Driver overheating: DERATING

When the temperature of the driver components overtakes a defined temperature threshold, the performance is automatically reduced to decrease the heating. It is possible to check in real time the temperature by reading the **Input Register 15**.
If it is not possible to reach a steady thermal equilibrium, the driver shuts down. The protection acts limiting the current to the motor. In this condition the driver goes in alarm (see chapter 18).
Once the temperature on the driver decreases under 75°C, the alarm is automatically reset.

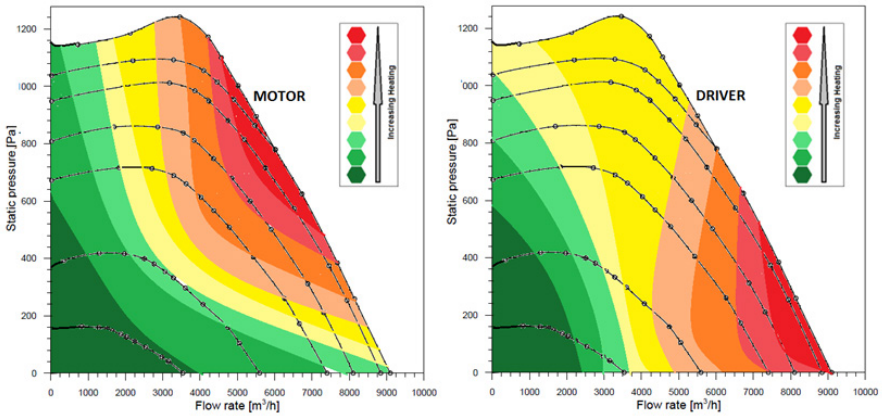
14.2 Motor overheating: THERMAL PROTECTOR

The motor is protected through one or more Thermal Protectors. If the motor temperature is too high, the thermal protector opens one phase and the driver recognizes the error and stops the fan (see chapter 18).

The Motor Winding temperature and the driver derating are dependent on the fan size and on the fan working point. Therefore, it is possible that the fan could work at 50°C without a performance limitation.

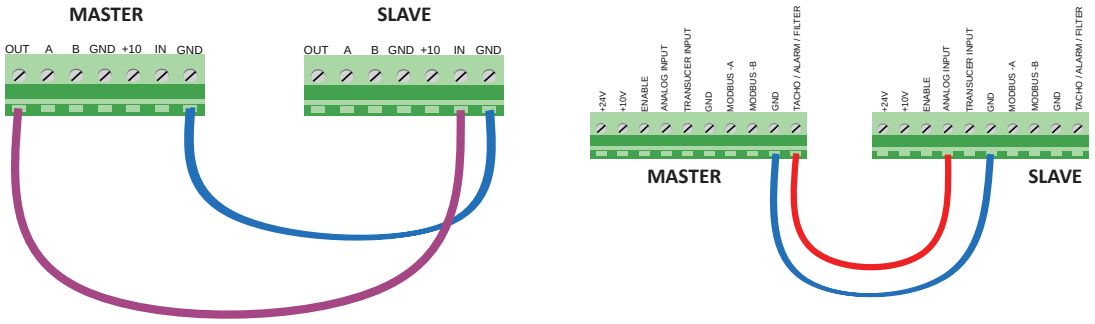
WARNING

The Driver and motor areas are rated for operating in a temperature range between -20°C and +40°C. The derating is tested and guaranteed from +40°C to +50°C.
Higher temperatures could damage the motor winding or the performance could be significantly reduced.



15. MASTER & SLAVE MODE

A Master & Slave connection is necessary when the fans have to operate in parallel and in any Constant-Airflow mode, or under control of the internal PID regulator. Having two or more fans self-controlling independently, while operating in parallel, can make the system unstable. A Master & Slave connection is neither needed nor recommended when the fans in parallel are runnig in any speed-control mode, even if under control of a common external PID regulator.



15.1 Master and Slave 0-5V PWM out [for 1.05 kW 1-phase only]

This single-phase driver has a tachometric output ranging from 0 to 5V and a special configuration must be set on the slave fan for a Master&Slave connection. It is possible to drive two fans in a master and slave configuration by setting the MASTER in any preferred mode and the SLAVE in Master&Slave mode only.
The SLAVE operating mode must be changed (**INPUT TYPE = 3**).
The MASTER must have the **Holding Register 46** set at 0 = TACHO.

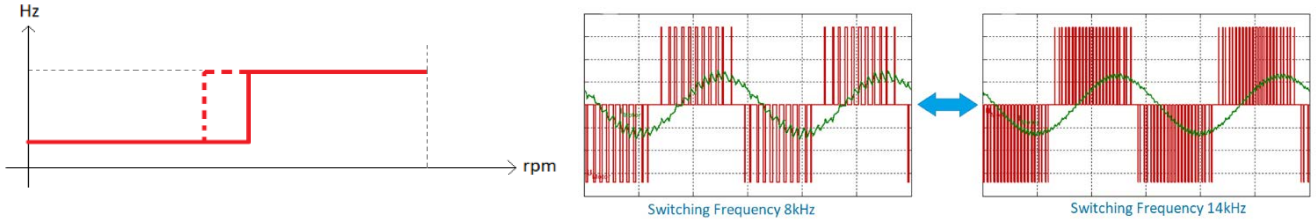
15.2 Master and Slave 0-10V PWM out [for other drivers]

The three-phase drivers can be connected in master & slave mode more easily. The three-phase drivers have a tachometric output ranging from 0 to 10 V.
The master can have any possible configuration, while the slave must be configured in Analog Speed Control only.
The MASTER must have the **Holding Register 46** set at 0 = TACHO.

With three-phase drivers connected in a master & slave arrangement, DO NOT set the slave driver in Master&Slave mode: if the slave is set in Master&Slave mode, it runs at twice the speed of the master.

16. VARIABLE SWITCHING FREQUENCY [for 3-phase - 4 kW only]

This feature is used to increase the efficiency and to decrease the heating of the fan. At slow fan speed the driver switching frequency is set at its maximum value 14kHz, while at high speed, the switching frequency is reduced to 8kHz. In this situation the noise generated by the lower switching frequency is covered by the higher fan noise.



17. COMMUNICATION

When trying to enter a value in any holding register, the value is not overwritten if the new value is outside the load boundaries.

The value of the Holding Registers is NOT coerced if trying to set a not allowed value.

Protocol interface:
MODBUS RTU (RS485 or Bluetooth)

Baud rate
The baud rate can be set through the **Holding Register 47** and the possible speeds are:
RS-485 CABLE: 9.6kbps and 19.2kbps (higher speeds are not allowed due to the board Opto-Insulators)
UART OFFLINE CABLE: 9.6kbps, 19.2kbps, 38.4kbps and 57.6kbps.

Parity and Stop bits
The parity and the stop bits can be chosen by modifying the **Holding Register 48** and the possible choices are:

0	**No parity, 2 Stop Bits (default)**
1	**Odd parity, 1 Stop Bit**
2	**Even parity, 1 Stop Bit**

Supported Function:

03	**Read Holding Registers**
04	**Read Input Registers**
06	**Write Single Holding Register**

Modbus Communication Timeout
With this feature it is possible to stop the fan when the communication is lost, after a period of time set in the **Holding Register 56**. The register can be set to:

0	**No Communication Timeout**
1 to 32767	**Time expressed in seconds, therefore it is possible to set from 1sec to 9h 6m 8 sec**

When the timeout occurs, the driver goes in alarm condition and the communication must be restored and the alarm must be cleared. The alarm is indicated in the Input register 17 with the value of 255 (0xFF).

Modbus Address
The slave device address can be changed from value 1 to 247 by modifying the **Holding Register 45**.
The default address from factory configuration is 1.

Broadcast Address
The Broadcast address is 0.

RS-485 Default Communication Parameters

	1-Phase		3-Phase	
	1.05kW	**2.1kW**	**2.65kW**	**4kW**
Baud rate	9600	9600	9600	9600
Parity and Stop Bits	0	0	0	0
Modbus Address	1	1	1	1

UART (OFFLINE) Default Communication Parameters

	1-Phase		3-Phase	
	1.05kW	**2.1kW**	**2.65kW**	**4kW**
Baud rate	9600	9600	57600	57600
Parity and Stop Bits	0	0	0	0
Modbus Address	1	1	1	1

Changing the Baud rate has an immediate effect, while the other communication parameters require the complete fan power off and consequently power on (wait until the complete discharge of the capacitors and the led turning off, otherwise the changes are not written into the EEPROM).

17.1 Temporary holding register

The **Holding Register 66** is a special register used in each operating mode for setting the speed, the airflow, the slip and the PID reference.
It is not a physical register and it can be written, but it is not possible to read its value. The setting remains active until the fan is powered on.

If the fan is powered off but there is a residual charge, the microcontroller of the driver is still functioning. Therefore, if it is powered on in this situation the value set through the register 66 is still active.

17.2 Fixed holding register

The drivers Holding Registers permanently stored into the EEPROM are 64, but only 26 registers are modifiable by the end user (see the table in the following page).
The most important **Holding Register 34** is the **Input Type** related to the selection of the Operating Mode.

0	Reset	43	Max Airflow
1	Min Speed	45	Modbus Address
2	Max Speed	46	Tacho\Alarm\Filter
7	Max Current	47	Modbus Baud rate
21	Fixed Speed Setting	48	Modbus Parity and Stop Bits
30	Asynchronous Slip Setting	50	External PID Setting
31	PID positive/negative	51	PID Kp
32	Avoid Range Start	52	PID Ki
33	Avoid Range End	53	PID Kd
34	Input Type	54	PID Time
36	Max Power Out	55	Speed Threshold
39	Constant Airflow Setting	56	Communication Timeout
42	Min Airflow		

17.3 Holding register description

CAUTION

The Holding Register must be set with the fan stopped.
Changing the parameters while the fun is running may cause unexpected behavior.

WARNING

Do not set the values outside the indicated limits, the driver could stop working without any alarm indication, it could be reset or work in an undefined condition.

If the below reported "Allowed values" are written between square brackets, they must be read as "maximum" and "minimum".

Holding Register 0: **RESET [Adim]**
This register can be used to reset the fan by writing the value 1 on it. This register automatically retun to value 0 after being reset. The driver will reset any error condition and it will try to restart.

Allowed values = 0 and 1	**Default value** = 0

Holding Register 1: **Min Speed [RPM]**
This register is used to set the minimum speed of the fan.

Allowed values = [Default Value, Max Speed]	**Default value** = table below

		7/7T	7/7	7/9	8/7T	9/7	8/9T	225/240	9/9	10/8	10/10	12/9	12/12	15/11	15/15
1.05kW	**1-Phase**	400	400	400	400	400	400	400	400	400	400	-	-	-	-
2.1kW	**1-Phase**	-	-	-	-	-	-	-	300	300	300	300	300	-	-
2.65kW	**3-Phase**	-	-	-	-	-	-	-	200	200	200	300	300	-	-
4kW	**3-Phase**	-	-	-	-	-	-	-	-	-	-	-	*	*	*

* The value is under development.

Holding Register 2: **Max Speed [RPM]**
This register can be used to set the max speed of the fan.

Allowed values = [Min Speed, Default Value]	**Default value** = table below

		7/7T	7/7	7/9	8/7T	9/7	8/9T	225/240	9/9	10/8	10/10	12/9	12/12	15/11	15/15
1.05kW	**1-Phase**	3000	2000	2000	2000	2000	2000	2000	2000	2000	2000	-	-	-	-
2.1kW	**1-Phase**	-	-	-	-	-	-	-	2000	2000	2000	1600	1600	-	-
2.65kW	**3-Phase**	-	-	-	-	-	-	-	2000	2000	2000	1600	1600	-	-
4kW	**3-Phase**	-	-	-	-	-	-	-	-	-	-	-	*	*	*

* The value is under development.

Holding Register 7: **Max Current [mA]**
This register can be used to reduce the max motor current.

Allowed values = [1, Default value]	**Default value** = table below

Although the value of the Max Current can be set at any value being lower than the original default one, it is not recommended using a value that is 0.3 times below the default one.

		7/7T	7/7	7/9	8/7T	9/7	8/9T	225/240	9/9	10/8	10/10	12/9	12/12	15/11	15/15
1.05kW	**1-Phase**	6000	4500	4500	4500	4500	4500	4500	4500	5500	5500	-	-	-	-
2.1kW	**1-Phase**	-	-	-	-	-	-	-	8300	8300	8300	8300	8300	-	-
2.65kW	**3-Phase**	-	-	-	-	-	-	-	8000	8000	8000	8000	8000	-	-
4kW	**3-Phase**	-	-	-	-	-	-	-	-	-	-	-	*	*	*

* The value is under development.

Holding Register 16: **Speed Threshold Low [RPM]**
This register can be used to set the speed threshold low.
The register is active when the **register 46** is set to the value 3.

Allowed values = [0, Speed Threshold High]	**Default value** = 0

Holding Register 21: **Fixed Speed setting [RPM]**
This register can be used to set the speed in **Fixed Speed Control Mode**.
The register is active when the Input Type **Holding Register 34** is set to the value 2.

Allowed values = [Min Speed, Max Speed]	**Default value** = 0

Holding Register 30: **Asynchronous Slip. [%]**
This register can be used to set the slip of an emulated ACIM motor.
The register is active when the Input Type Holding Register is set to the value 9.

Allowed values = [0, 100]	**Default value** = 0

Holding Register 31: **PID Positive/Negative [Adim]**
This register can be used to invert the feedback behavior of the PID.

Allowed values = 0 and 1	**Default value** = 0

Holding Register 32: **Avoid Range Start [RPM]**
This register combined with the Avoid Range End can be used to skip some resonance frequencies of the fan.

Allowed values = [0, Avoid Range End]	**Default value** = 20000

Holding Register 33: **Avoid Range End [RPM]**
This register combined with the Avoid Range Start can be used to skip some resonance frequencies of the fan.

Allowed values = [Avoid Range Start, 20000]	**Default value** = 20000

Holding Register 34: **Input Type [Adim]**
This register defines all the possible operating modes:

Allowed values = [0,12]	**Default value** = 1

0	Modbus Speed Control	The speed is set by modifying the register 66
1	Analog Speed Control	The speed is set through the analog signal
2	Modbus Fixed Speed Control	The speed is set by modifying the register 21
3	Master&Slave	The fan is configured as slave and follows the master
4	Analog Constant Airflow	The constant airflow is set through the analog signal
5	Modbus Temporary Constant Airflow	The constant airflow is set by modifying the register 66
6	Modbus Fixed Constant Airflow	The constant airflow is set by modifying the reg. 39
7	Analog Asynchronous Emulation	The emulation is set through the analog signal
8	Modbus Temporary Asynchronous Emulation	The emulation is set by modifying the register 66
9	Modbus Fixed Asynchronous Emulation	The emulation is set by modifying the register 30
10	Analog Ref. PID Closed Control Loop	The PID ref. is set through the analog signal
11	Modbus Temporary Ref. PID Closed Control Loop	The PID ref. is set by modifying the register 66
12	Modbus Fixed Ref. PID Closed Control Loop	The PID ref. is set by modifying the register 50

Holding Register 36: **Maximum Power [W]**
This register can be set to reduce the power out to the motor.

Allowed values = [10, Default Value]	**Default value** = table below

		Value
1.05kW	**1-Phase**	1050
2.1kW	**1-Phase**	2100
2.65kW	**3-Phase**	2650
4kW	**3-Phase**	4100

Holding Register 39: **Constant Airflow [m3/h]**
This register can be used to set the constant airflow value.
The register is active when the Input Type Holding Register is set to the value 6.

Allowed values = [Min Airflow, Max Airflow]	**Default value** = 0

Holding Register 42: **Min Airflow [m3/h]**
This register can be used to set the min constant airflow.

Allowed values = [Default Value, Max Airflow]	**Default value** = table below

		7/7T	7/7	7/9	8/7T	9/7	8/9T	225/240	9/9	10/8	10/10	12/9	12/12	15/11	15/15
1.05kW	**1-Phase**	1000	500	1000	750	1000	1000	1000	1000	1000	1000	-	-	-	-
2.1kW	**1-Phase**	-	-	-	-	-	-	-	1000	1000	1000	1500	1500	-	-
2.65kW	**3-Phase**	-	-	-	-	-	-	-	1000	1000	1000	1500	1500	-	-
4kW	**3-Phase**	-	-	-	-	-	-	-	-	-	-	-	*	*	*

* The value is under development.

Holding Register 43: **Max Airflow [m3/h]**
This register can be used to set the min constant airflow.

Allowed values = [Default Value, Max Airflow]	**Default value** = table below

		7/7T	7/7	7/9	8/7T	9/7	8/9T	225/240	9/9	10/8	10/10	12/9	12/12	15/11	15/15
1.05kW	**1-Phase**	1950	3000	3500	2750	3000	3250	3250	3250	3750	4000	-	-	-	-
2.1kW	**1-Phase**	-	-	-	-	-	-	-	5000	4500	5000	4500	5000	-	-
2.65kW	**3-Phase**	-	-	-	-	-	-	-	5000	4500	5000	5000	5000	-	-
4kW	**3-Phase**	-	-	-	-	-	-	-	-	-	-	-	*	*	*

* The value is under development.

Holding Register 45: **Modbus Address [Adim]**
This register can be used to change the Modbus address of a driver.

Allowed values = [1, 247]	**Default value** = 1

Holding Register 46: **Tachometric / Alarm / Threshold [Adim]**
This register can be used to set the digital output function.

Allowed values = table below	**Default value** = 0

The possible settings are:

0	**Tachometric**	The digital output indicates the measured speed through a PWM signal
1	**Alarm**	The digital output indicates when an alarm occurs
2	**Threshold**	The digital output indicates when the speed set in the Holding Register 55 is overtaken
3	**Out of Functioning Range**	The digital output indicates when the fan is working in a defined range of speeds

Holding Register 47: **Modbus Speed [10^{-1} kbps]**
This register can be used to set the Modbus speed.

Allowed values = table on the following page	**Default value** = 96

96	corresponding to 9.6kbps
192	corresponding to 19.2kbps
384	corresponding to 38.4kbps (not available using the opto-insulated terminal block)
576	corresponding to 57.6kbps (not available using the opto-insulated terminal block)

Holding Register 48: **Modbus Stop Bits [Adim] (Default = 0)**
This register can be used to set the parity and the stop bits.

Allowed values = table below	**Default value** = 0

0	2 Stop Bits/No Parity
1	1 Stop Bit/Even Parity
2	1 Stop Bit/Odd Parity

Holding Register 50: **External Set [10^{-1} V]**
This register can be used to set the reference of the PID control.

Allowed values = [0, 100]	**Default value** = 0

The register is active when the Input Type Holding Register is set to the value 12.

Holding Register 51: **Kp [Adim]**
This register can be used to set the Proportional Gain of the PID control.

Allowed values = [0, 32767]	**Default value** = 0

Holding Register 52: **Ki [Adim]**
This register can be used to set the Integral Gain of the PID control.

Allowed values = [0, 32767]	**Default value** = 0

Holding Register 53: **Kd [Adim]**
This register can be used to set the Derivative Gain of the PID control.

Allowed values = [0, 32767]	**Default value** = 0

Holding Register 54: **Period [ms]**
This register can be used to set the time constant of the PID control.

Allowed values = [0, 32767]	**Default value** = 0

Holding Register 55: **Speed Threshold (or Speed Threshold HIGH) [RPM]**
This register can be used to set the speed threshold, when the measured speed in the Input Register 3 overtakes the threshold value.

Allowed values = [0, Max Speed]	**Default value** = 0
Allowed values (Functioning Indication mode) = [Speed Threshold Low, Max Speed]	

Speed Threshold =0 means that it is **DEACTIVATED**

Holding Register 56: **Communication Timeout [s]**
This register can be used to set a timeout period for the communication.

Allowed values = [0, 9hour 8min 8sec]	**Default value** = 0

At the end of the period set into the register the fan stops and there is an Alarm indication. To restart a reset command must be sent.
Communication Timeout =0 means that it is **DEACTIVATED**

17.4 Input register description

The Modbus Input Registers are in total 33, but only 14 are useful for the end user.

2	Speed Reference	[rpm]		**15**	Module Temperature	[10^{-1} °C]
3	Measured Speed	[rpm]		**17**	Alarm 2	[Adim]
9	Bus Voltage	[10^{-1}V]		**28**	Enable Input	[10/2^{16} V]
10	Alarm 1	[Adim]		**29**	Analog Input	[10/2^{16} V]
12	Motor Current	[mA]		**30**	Transducer Input	[10/2^{16} V]
13	Motor Voltage	[10^{-1}V]		**31**	Measured Power	[W]
14	Analog Input	[10^{-1}V]		**32**	Input Current	[mA]

Input Register 2: **Speed Reference [rpm]**
This register indicates the speed reference during the functioning. During the starting phase, it is equal to the Min Speed and then gradually increases to the target speed depending on the selected mode.

Input Register 3: **Measured Speed [rpm]**
This register indicates the speed during the functioning.

Input Register 9: **Bus Voltage [10^{-1} V]**
This register indicates the rectified voltage after the PFC stage.

Input Register 10: **Alarm 1 [Adim]**
This register must be combined with the Alarm2 register (see the table in paragraph 18.2)

Input Register 12: **Motor Current [mA]**
This register indicates the peak value of the line current module.
To know the rms value, it must be divided by √2.

Input Register 13: **Motor Voltage [10^{-1} V]**
This register indicates the peak value of the phase voltage module.
To know the rms line to line value, it has to be multiplied by √3/2.

Input Register 14: **Analog Voltage [10^{-1} V]**
This register indicates the analog voltage value present at the input.

Input Register 15: **Module Temperature [10^{-1} °C]**
This register indicates the temperature of the power module of the driver. When the value exceeds the temperature threshold, the driver enters in a derating process where the performances are automatically decreased until a thermal equilibrium below the temperature threshold is reached. If this equilibrium is not reached, the fan stops and an alarm condition is activated. As soon as the heating decreases and the power module temperature is below the temperature threshold, the alarm is automatically reset.
This threshold value can be read in *Holding Register 29*.

Input Register 17: **Alarm 2 [Adim]**
This register must be combined with the Alarm1 register.

Input Register 28: **Enable Input [Adim]**
This input indicates the ENABLE state.
The value must be multiplied by $10V/2^{16}$ to have the corresponding voltage value.

Input Register 29: **Analog Input [Adim]**
This input indicates the Reference Value.
The value must be multiplied by $10V/2^{16}$ to have the corresponding voltage value.

Input Register 30: **Transducer Input [Adim]**
This input indicates the Transducer Value.
The value must be multiplied by $10V/2^{16}$ to have the corresponding voltage value.

Input Register 31: **Measured Power [W]**
This register indicates the absorbed power.

Input Register 32: **Input Current [mA]**
This input indicates the input absorbed current.

17.5 Fan info and Modbus registers

The **Holding Register 44** indicates the fan model.

		7/7T	7/7	7/9	8/7T	9/7	8/9T	225/240	9/9	10/8	10/10	12/9	12/12	15/11	15/15
1.05kW	**1-Phase**	1	2	3	4	5	6	7	8	9	10	-	-	-	-
2.1kW	**1-Phase**	-	-	-	-	-	-	-	1	2	3	4	5	-	-
2.65kW	**3-Phase**	-	-	-	-	-	-	-	1	2	3	4	5	-	-
4kW	**3-Phase**	-	-	-	-	-	-	-	-	-	-	-	*	*	*

* The value is under development.

The **Input Register 0** indicates the driver firmware version and the **Input Register 1** indicates the driver model.

	1-Phase		3-Phase
	1.05kW	**2.1kW**	**2.65kW**
Firmware Version	5	5	6
Frequency Converter Model	41504	45600	45091
Frequency Converter Code	1431A5 1431F1	1431A8	1431G0

18. ALARM HANDLING

When a malfunctioning occurs, the driver has two possible behaviors depending on the cause of the alarm:

BLOCKING	The cause of the alarm is very dangerous -> The driver stops immediately. To restart the fan, once the problem has been corrected, it is necessary to reset the fan or power the driver off for 5 minutes.
AUTO-RESTARTING	The cause of the alarm is contingent to a wrong setting or wrong working condition. The alarm indications are activated, but after some seconds the fan tries to restart automatically.

18.1 Monitoring

The alarms can be monitored through three different ways:

- Modbus Registers
- Blinking LED
- Digital Output

18.2 Modbus registers - Alarm description

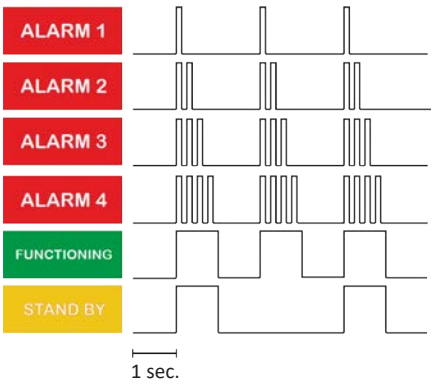
In the following table, the alarms and the values stored in the related Modbus **Input Register 10** and **Input Register 17** are indicated.

Alarm 1	Alarm 2	Description	Actions	Type
0	0	Default operation – No Errors	No Actions	ALARM 1
1	0	Memory error	Blocking condition	ALARM 2
2	0	Short Circuit	Blocking condition	ALARM 3
3	0	Loss of synchronism	Auto-restarting condition	ALARM 4
4	1	Input Voltage outside range (only with motor stopped)	Auto-restarting condition	ALARM 4
4	32	BUS overvoltage (instantaneous measurement)	Auto-restarting condition	ALARM 4
4	33	BUS undervoltage (instantaneous measurement)	Auto-restarting condition	ALARM 4
4	34	Input relay not closed	Auto-restarting condition	ALARM 4
4	49	Missing phase – U cable disconnected	Blocking condition	ALARM 4
4	50	Missing phase – V cable disconnected	Blocking condition	ALARM 4
4	51	Missing phase – W cable disconnected	Blocking condition	ALARM 4
4	52	High starting current	Auto-restarting condition	ALARM 4
4	113	Overtemperature	Auto-restarting condition	ALARM 4
4	255	Loss of communication	Blocking condition	ALARM 4

⚠ WARNING

The Driver is NOT protected against a very high-power supply voltage.
A very low power supply voltage during the motor running could damage Driver.

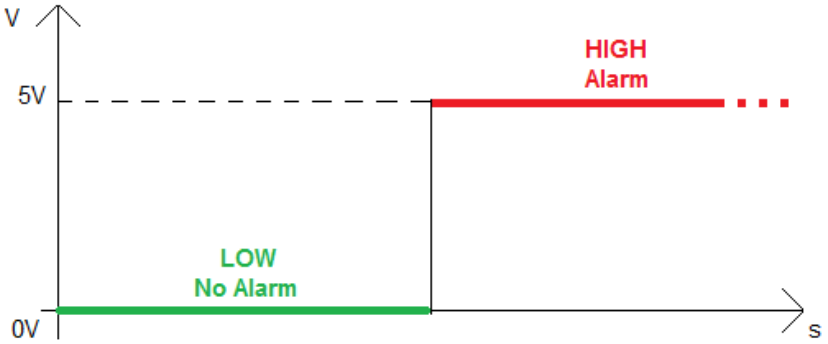
18.3 Blinking LED - Alarm description



The system status can be displayed through the LED on the driver plate (see par. 9.6). In the following figure on the right the blinking LED is shown.

18.4 Digital Alarm Output

The driver output can be configured as Alarm output by modifying the **Holding Register 46** to value 1. During the normal functioning, the value is 0V and, when an alarm occurs, the output value is 5V (or 10V depending on the fan model).



18.5 Alarm Reset

The alarms are automatically reset following the action of the table below:

Operating Mode	Input Type	Action
Analog	1, 4, 7, 10	Signal set to 0V
Fixed	2, 6, 9, 12	Registers 21, 39, 30 and 50 set to 0

As conerns the Temporary Modbus mode, it is necessary to reset the fan by setting the **Holding Register 0** to value=1 instead of setting to 0 the **Register 66**.

Temporary	0, 5, 8, 11	Register 0 set to 1

The Holding Register 0 is a general reset and works also in the Analog mode and Fixed mode.

19. AVAILABLE SOFTWARE

A freeware software is available on **Nicotra Gebhardt** site (http://www.nicotra-gebhardt.com) for monitoring the fan. Please refer to the related manual for more details

WARNING

The software can be used for configuring the fan and monitoring the performance.
The performance is estimated through an algorithm and, therefore, subjected to variable tolerance depending on the working point, airflow stability and the constant algorithm resolution itself.

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